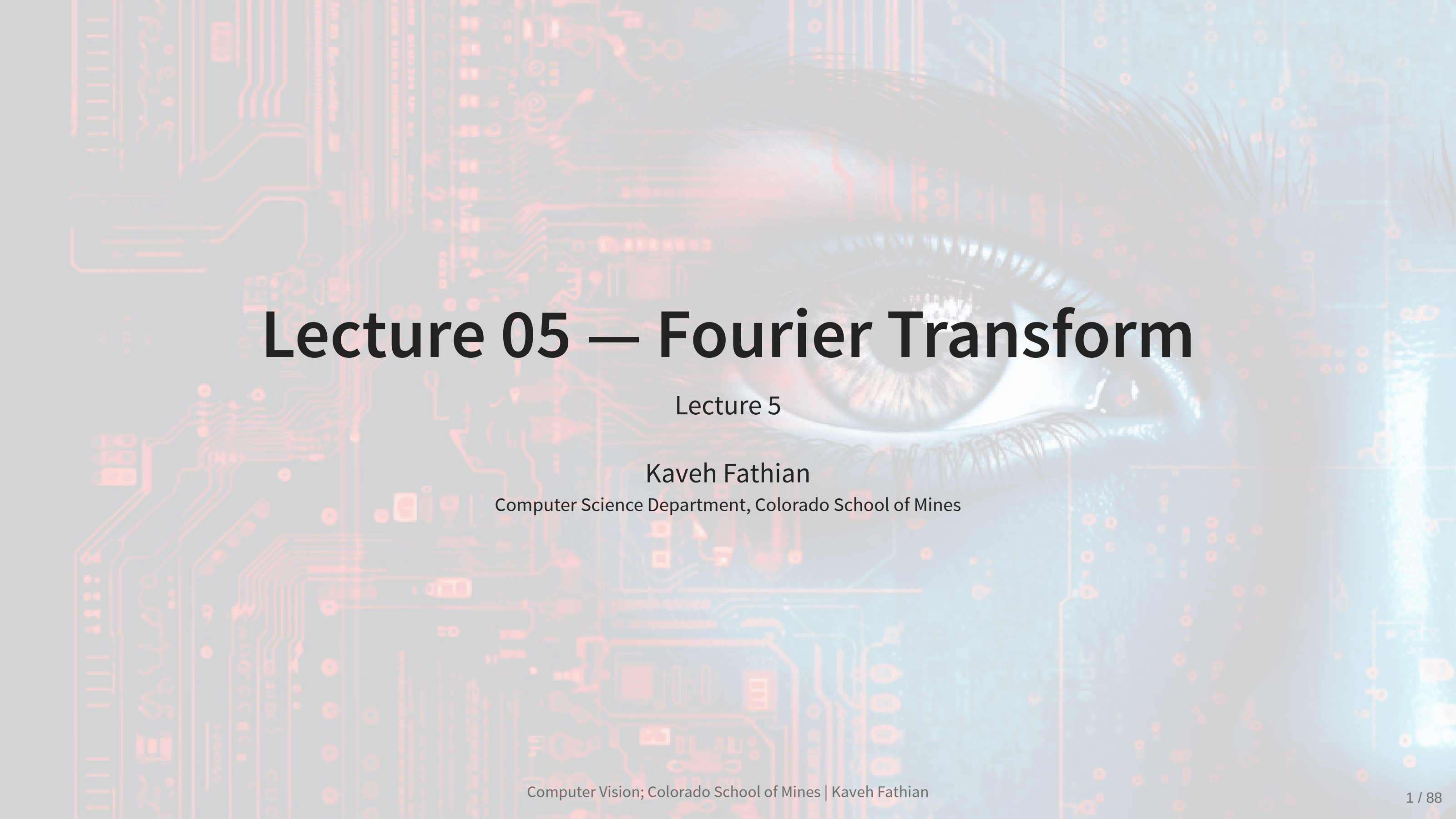




Lecture 05 — Fourier Transform

Lecture 5

Kaveh Fathian

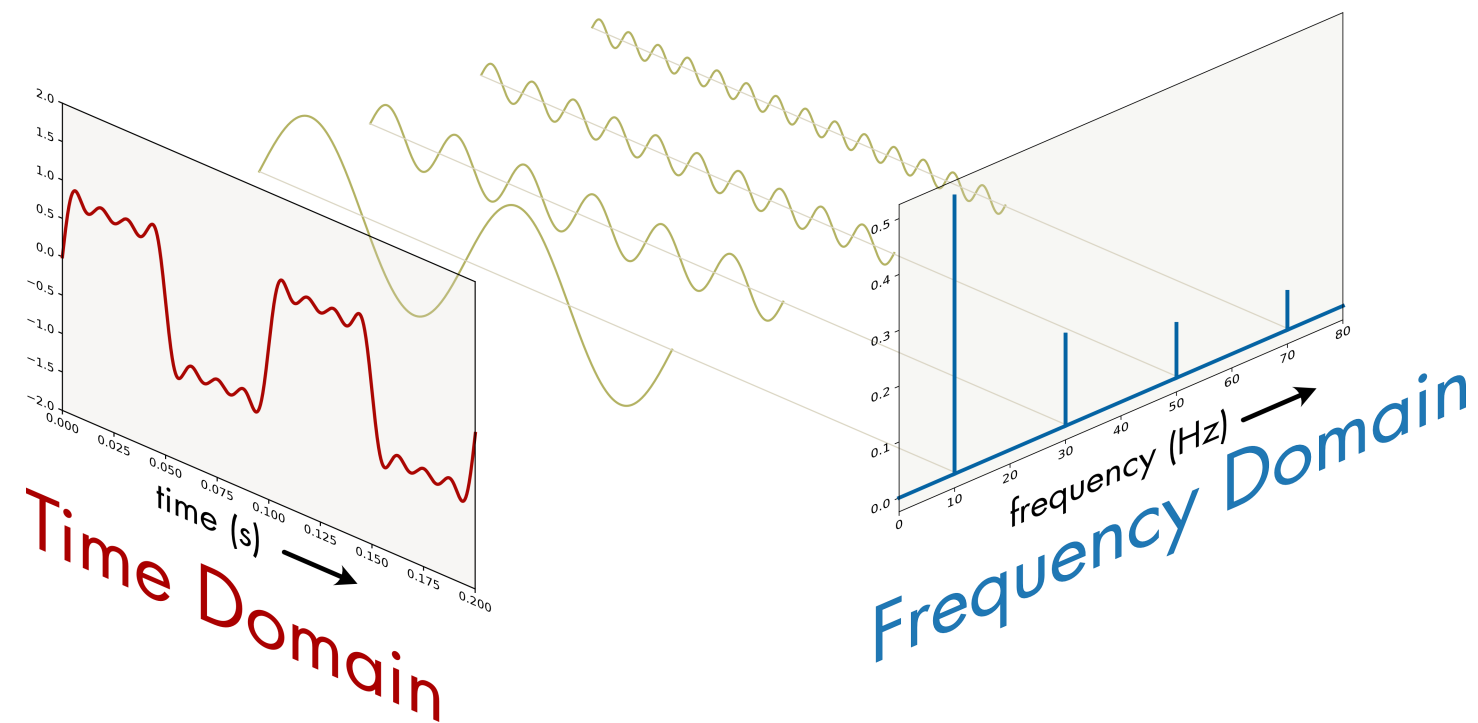
Computer Science Department, Colorado School of Mines

Learning Objectives

By the end of this lecture, you should be able to:

- Distinguish Fourier series, and the discrete Fourier transform (DFT)
- Interpret amplitude, phase, and frequency locations in an image spectrum.
- Predict how image structure, translation, rotation, and scale affect the Fourier transform.
- Reconstruct images from selected complex coefficients and explain the connection to compression.
- Apply the convolution theorem to image filtering, including our correlation convention.
- Explain aliasing using the Nyquist condition and choose low-pass filtering before downsampling.

Fourier Transform



Fourier's Idea

Can we build a complicated signal from simple waves?



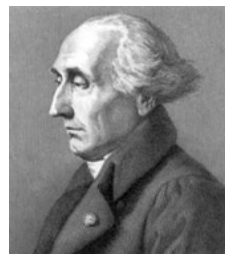
Joseph Fourier (1768–1830)

The Fourier series claim (1807):

Any univariate function can be rewritten as a weighted sum of sines and cosines of different frequencies.



Malus



Lagrange



Legendre



Laplace

- The initial reviewers (Lagrange, Laplace, Monge, and Lacroix) were **skeptical**, partly because the proofs lacked rigor. Publication of his work was initially withheld.
- The later committee, which included Lagrange, Laplace, Malus, and Legendre, awarded Fourier a prize but criticized the generality and rigor of his analysis.

Is Fourier's Claim True?

Well, almost.

The theorem requires additional conditions:

- A sufficient condition is that the function is **periodic and piecewise smooth**.
 - At continuous points, the series converges to the function's value.
 - At a jump, it converges to the **average of the values on either side**.

Very surprising result at the time, because it implied that

- Even signals with **sharp corners or jumps** can have a representation built from **smooth sine and cosine waves**.



Joseph Fourier

Basic Building Block

A sinusoid:

$$A \sin(\omega x + \phi)$$

- A : **amplitude** — controls the height of the oscillations.
- ω : **angular frequency** — controls how rapidly the signal oscillates.
- ϕ : **phase** — shifts the wave horizontally.
- x : **variable** — for example, time or spatial position.

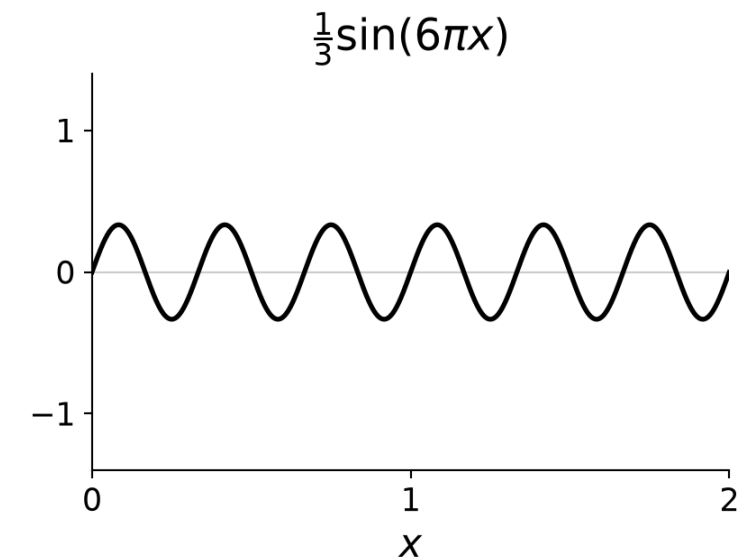
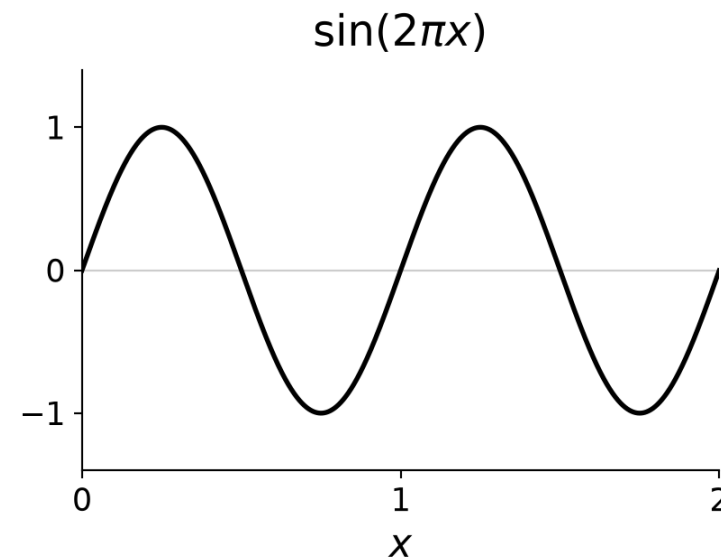
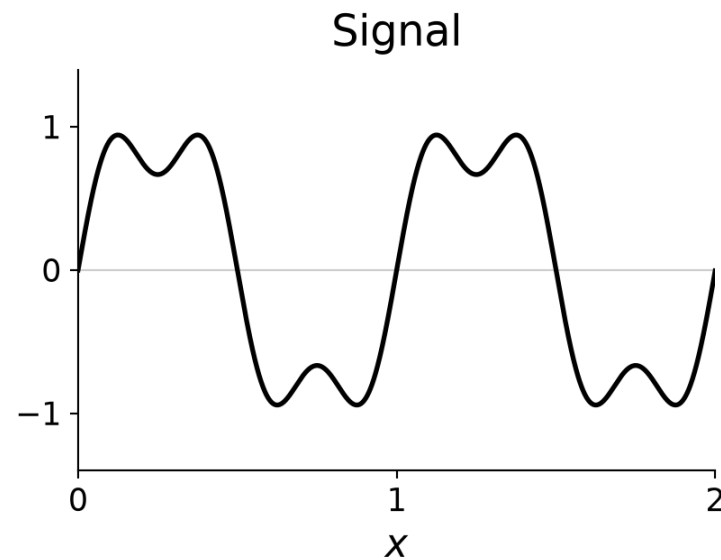
Fourier's idea: Build a **periodic** signal by adding sinusoids with different frequencies, amplitudes, and phases:

$$y(x) = c_0 + \sum_{k=1}^{\infty} A_k \sin(2\pi k f_0 x + \phi_k)$$

- c_0 : mean value.
- f_0 : fundamental frequency.

Example: Adding Sinusoids

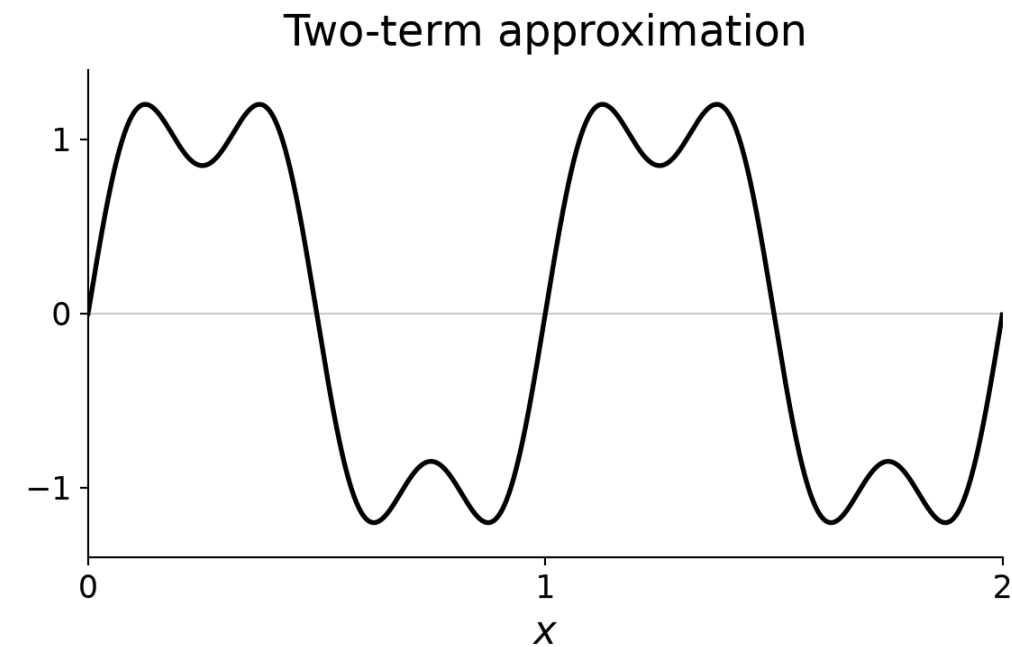
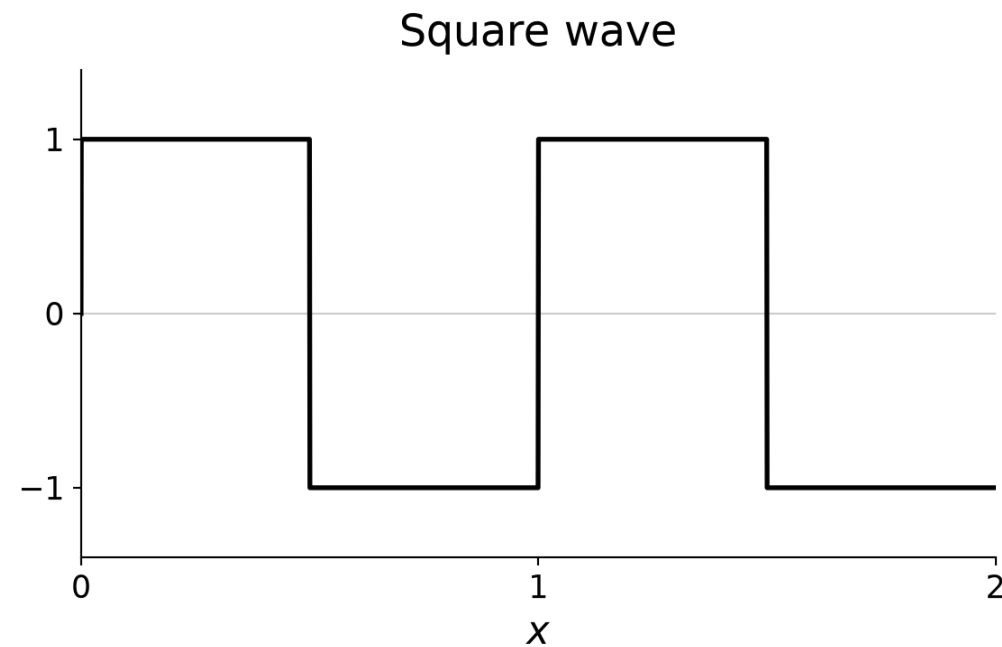
How would you generate this function?



$$y(x) = \sin(2\pi x) + \frac{1}{3}\sin(6\pi x)$$

Example: Approximating a Square Wave

How would you generate this function?



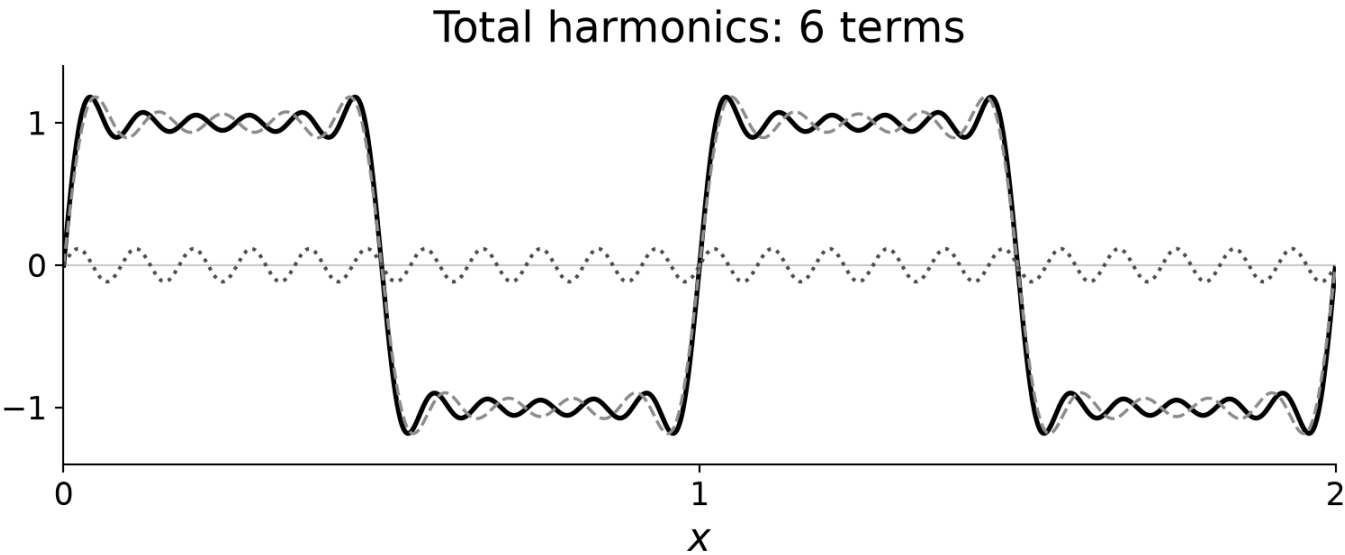
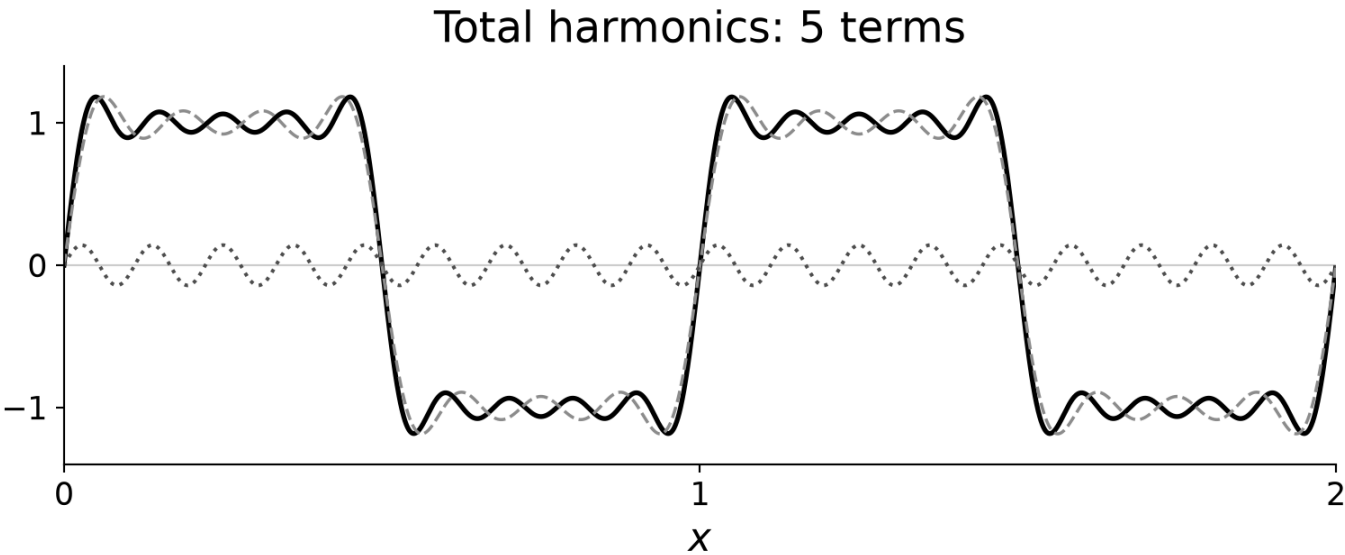
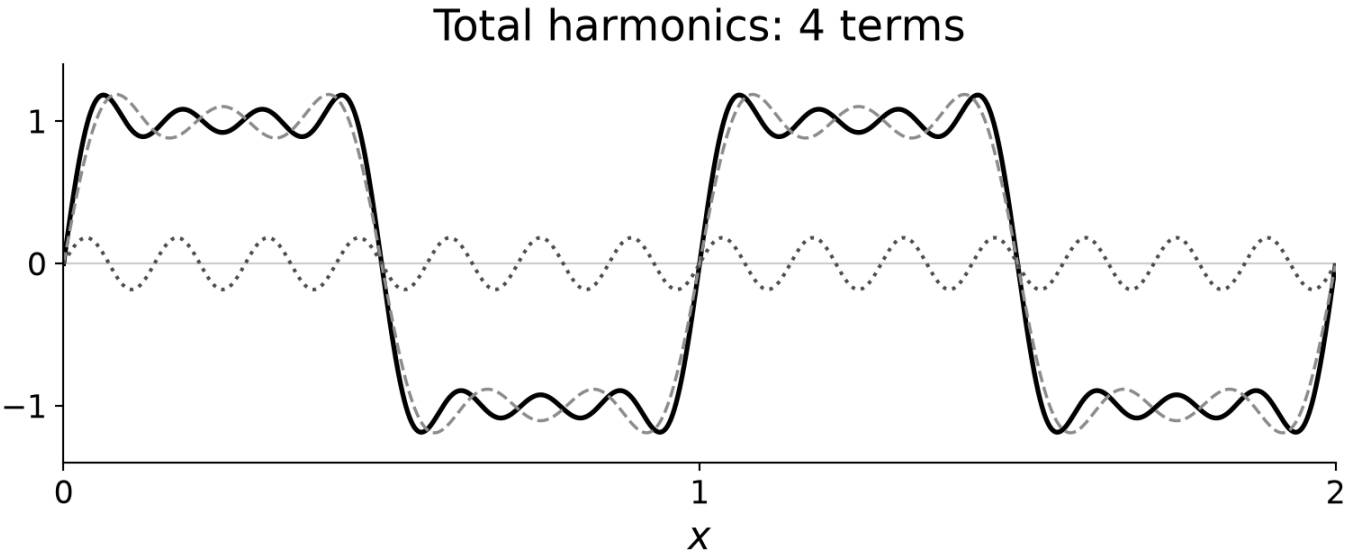
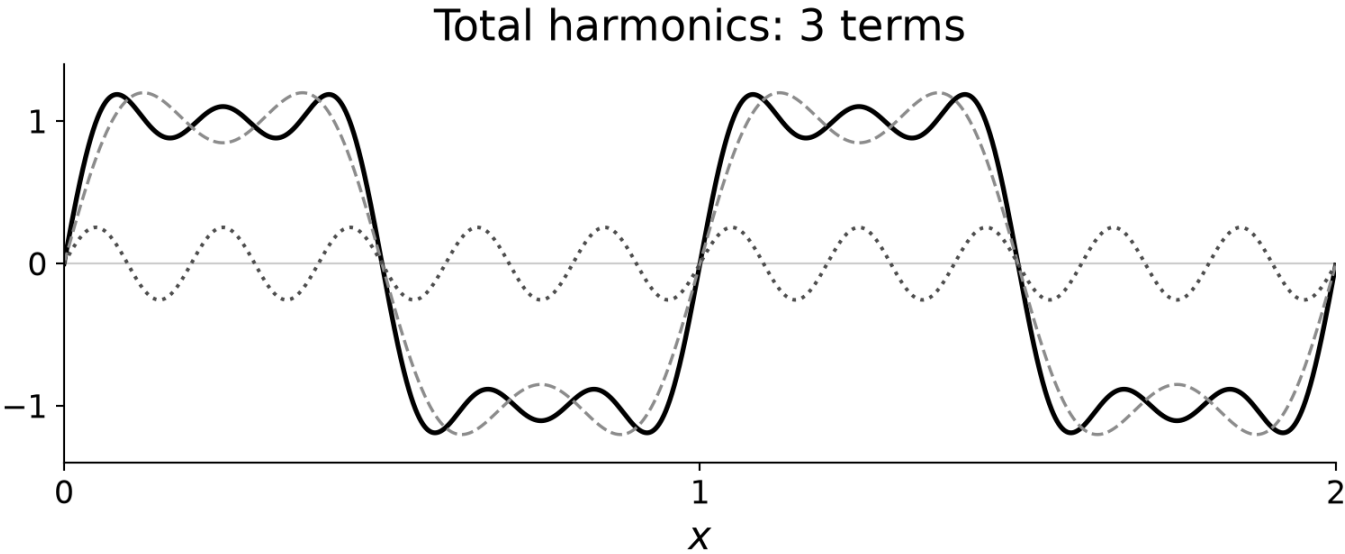
$$\frac{4}{\pi} \left[\sin(2\pi x) + \frac{1}{3} \sin(6\pi x) \right]$$

What happens if we add **higher-frequency sinusoids**?

Adding More Harmonics

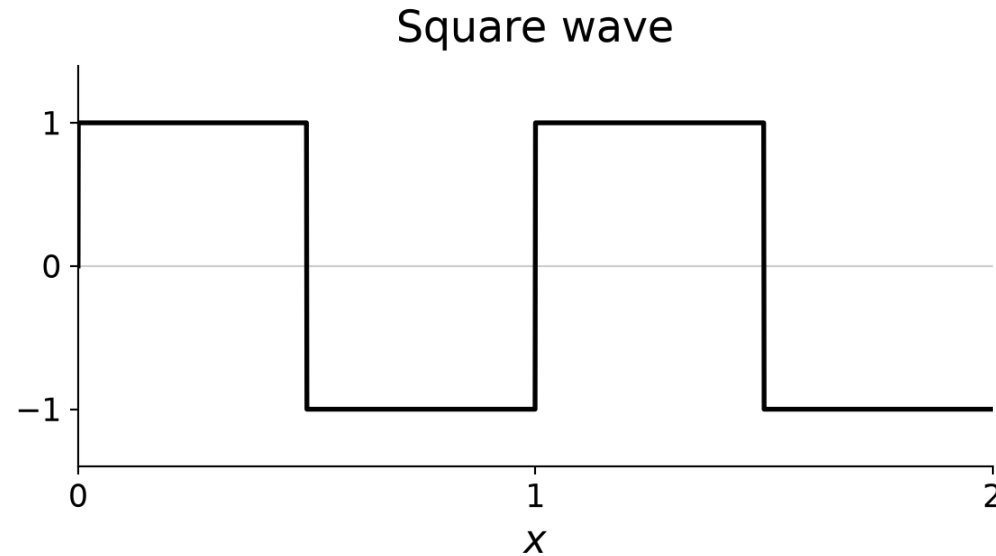
Add the next harmonic at each step:

— New sum - - - Previous sum . . . Added sinusoid



The Square-Wave Fourier Series

How would you express this mathematically?



General **Fourier series**:

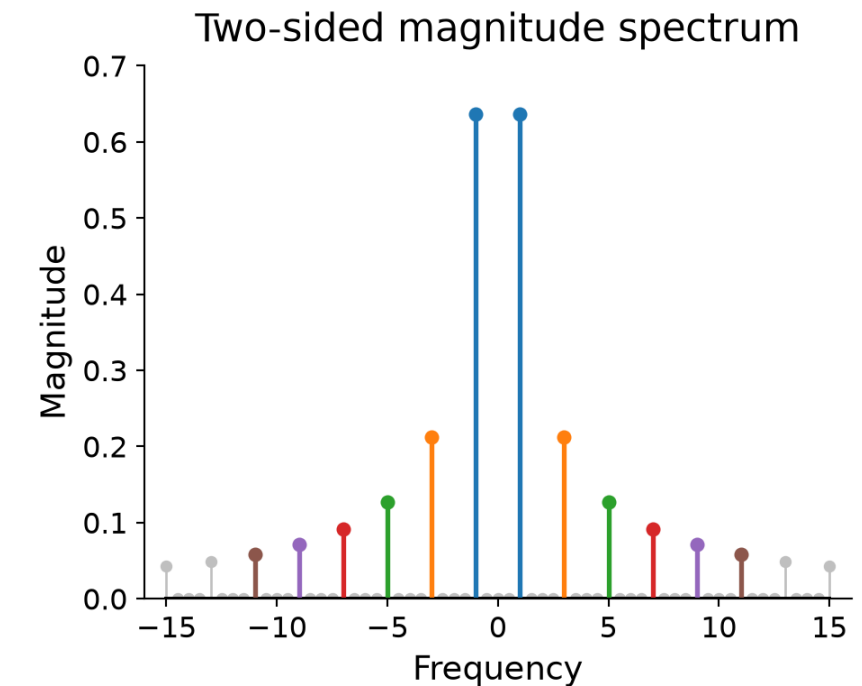
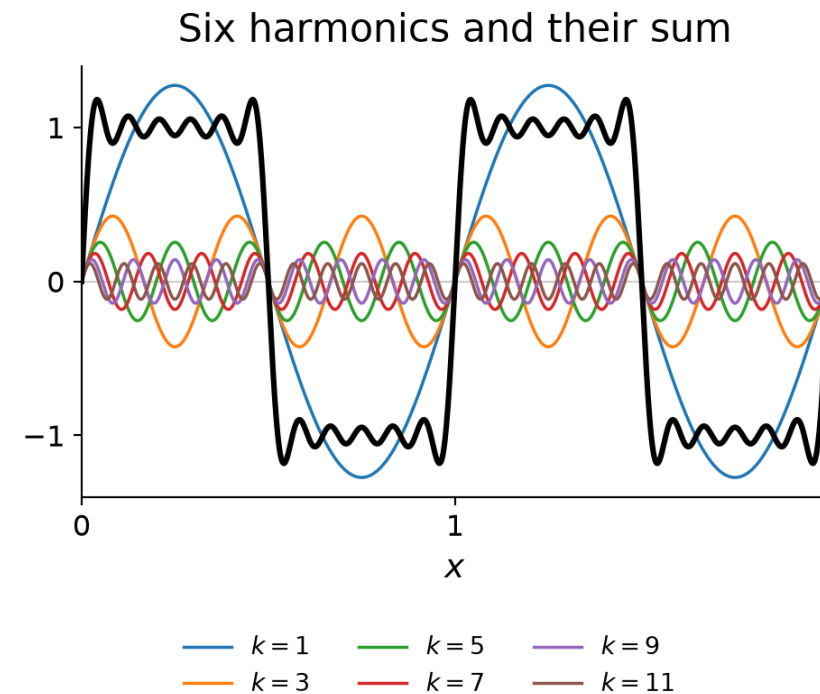
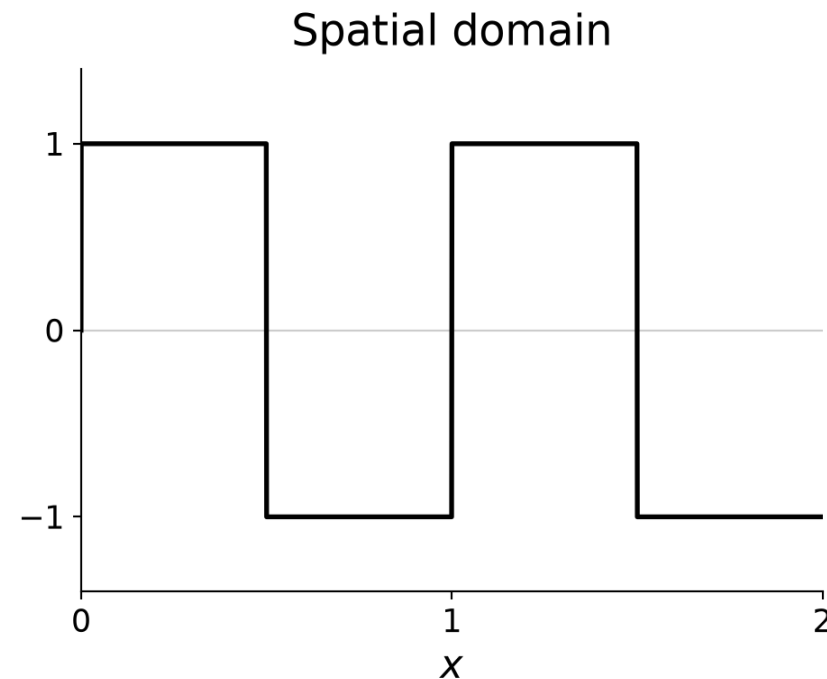
$$y(x) = c_0 + \sum_{k=1}^{\infty} A_k \sin(2\pi k f_0 x + \phi_k)$$

For this **square wave**, $c_0 = 0$ and $f_0 = 1$:

$$y(x) = \sum_{\substack{k=1 \\ k \text{ odd}}}^{\infty} \frac{4}{k\pi} \sin(2\pi k x)$$

- Frequencies: 1, 3, 5, 7, ...
- Amplitudes: $\frac{4}{\pi}, \frac{4}{3\pi}, \frac{4}{5\pi}, \dots$
- Phases: 0, 0, 0, ...

The Square Wave in the Frequency Domain

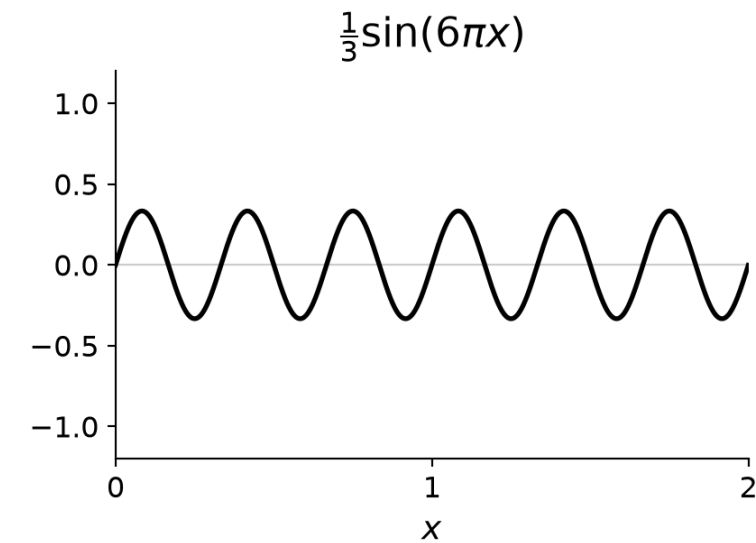
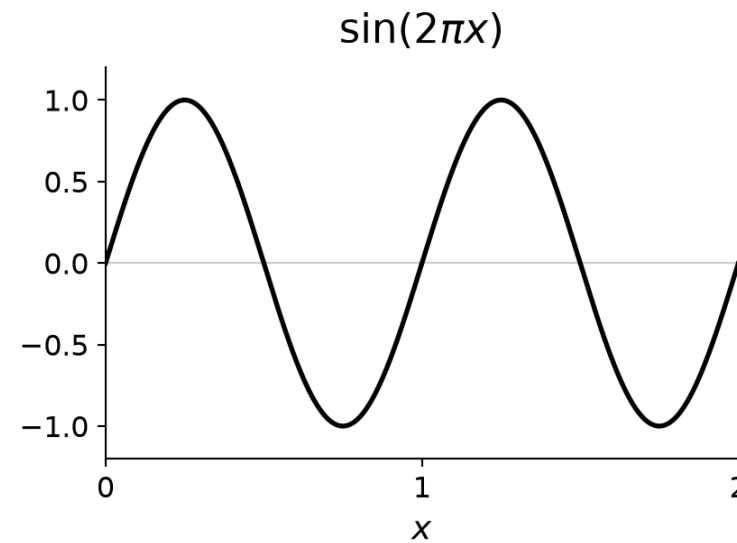
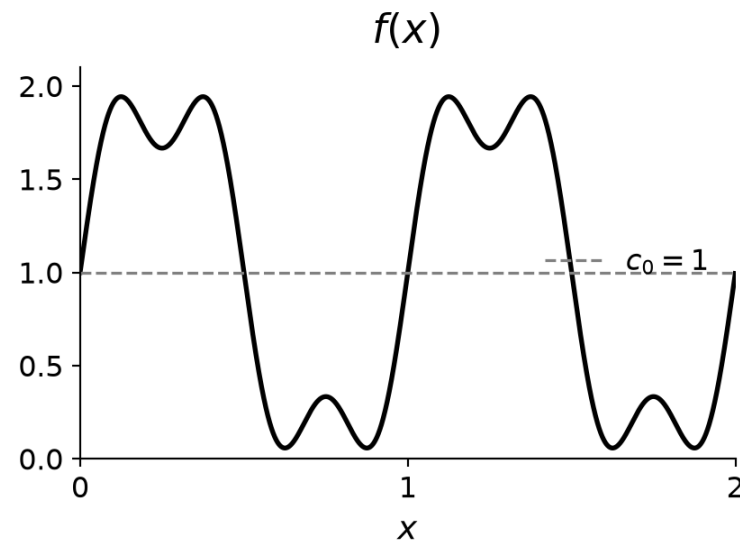


$$y_6(x) = \frac{4}{\pi}\sin(2\pi x) + \frac{4}{3\pi}\sin(6\pi x) + \frac{4}{5\pi}\sin(10\pi x) + \frac{4}{7\pi}\sin(14\pi x) + \frac{4}{9\pi}\sin(18\pi x) + \frac{4}{11\pi}\sin(22\pi x)$$

- Each sinusoid produces **two peaks** at frequencies $\pm f$. Matching colors connect each sinusoid to its peaks.
- The black curve in the middle shows the **six-term sum**; the ideal square wave requires **infinitely** many terms.

Visualizing the Frequency Spectrum

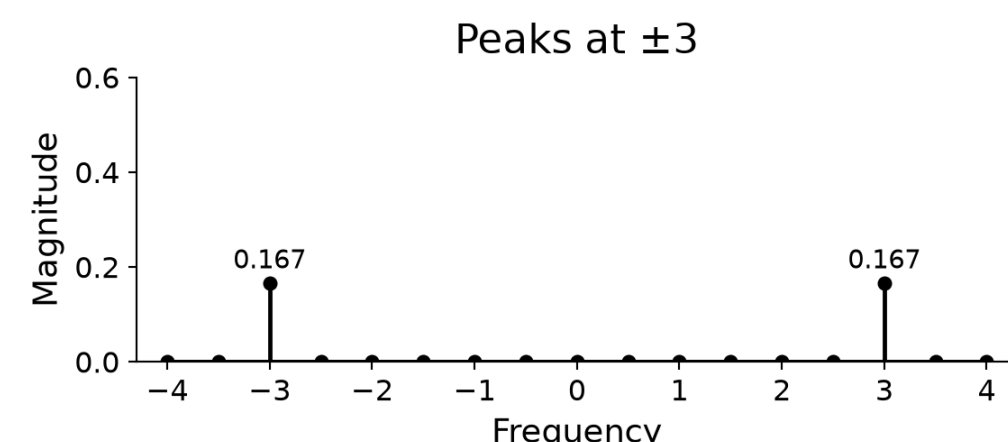
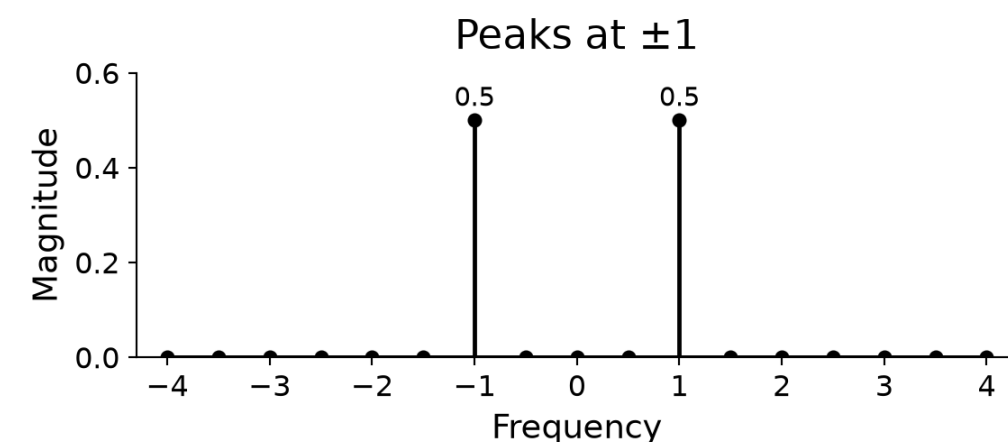
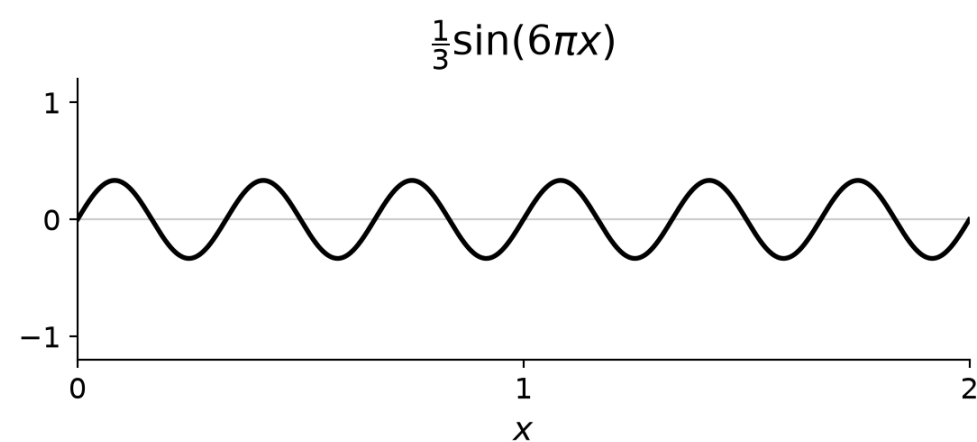
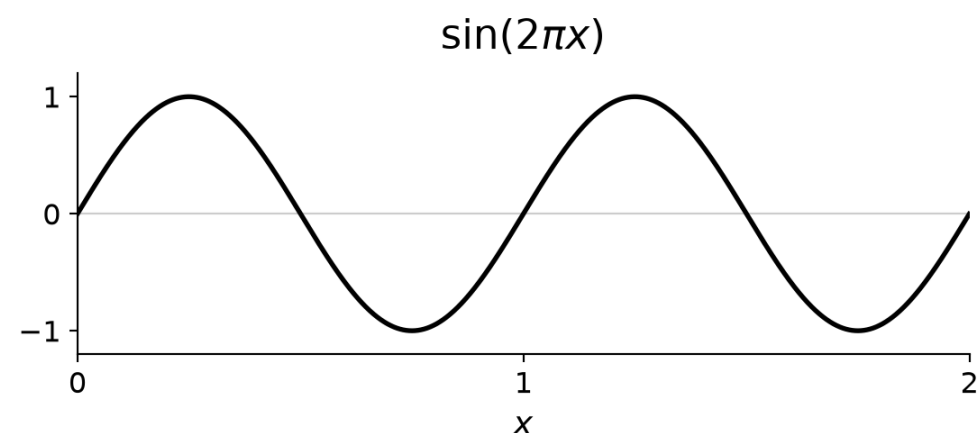
$$f(x) = c_0 + \sin(2\pi x) + \frac{1}{3}\sin(6\pi x), \quad c_0 = 1$$



The constant c_0 shifts the signal vertically without changing its oscillations.

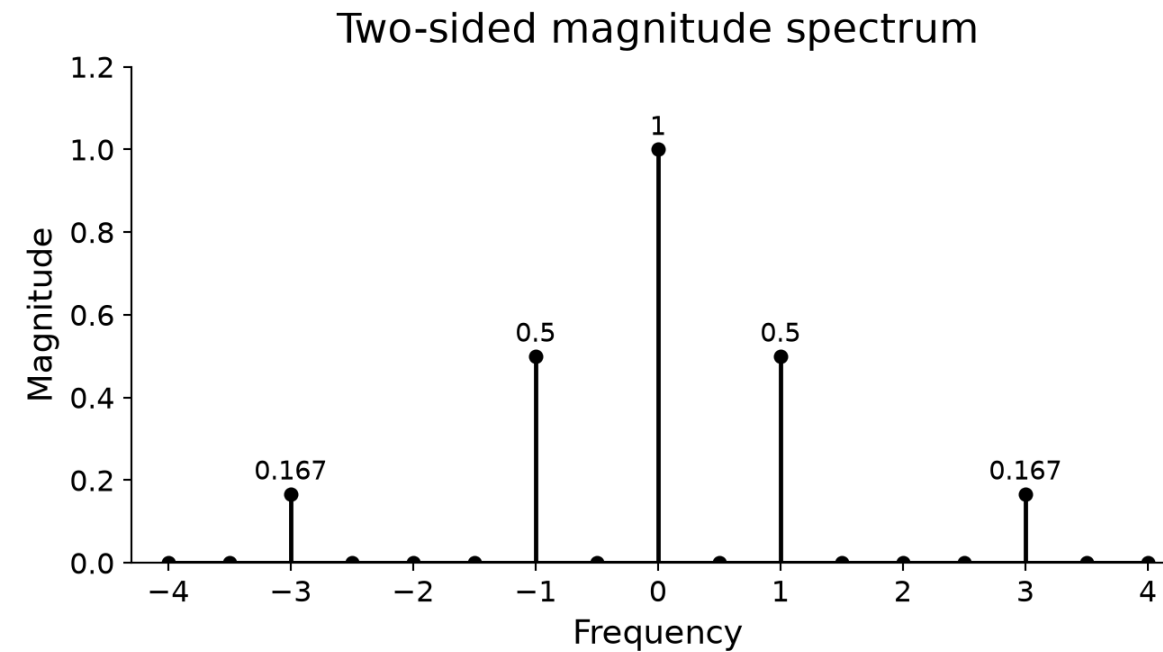
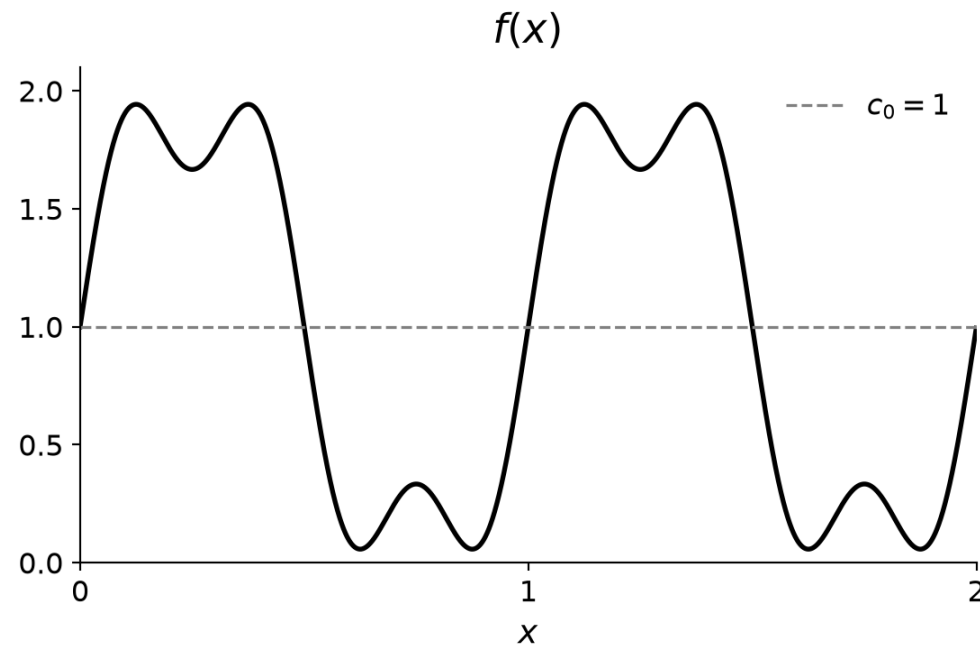
How does each term appear in the frequency domain?

Visualizing the Frequency Spectrum



A sinusoid of amplitude A produces **two peaks**, each of height $A/2$, at its positive and negative frequencies.

What Is at Zero Frequency?



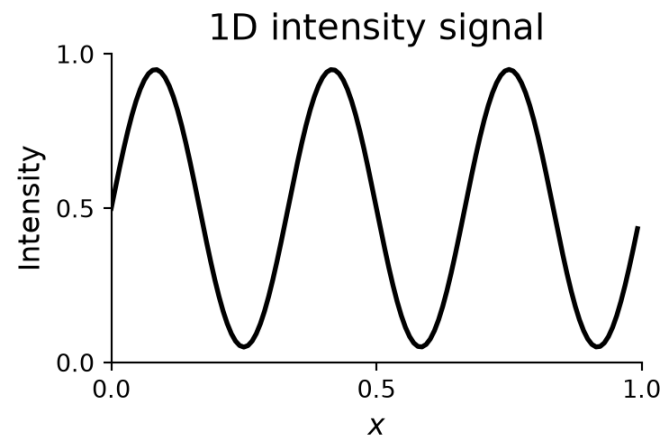
The **DC component** represents the signal's **mean value**.

$$c_0 = \frac{1}{N} \sum_{n=0}^{N-1} f(x_n) = 1$$

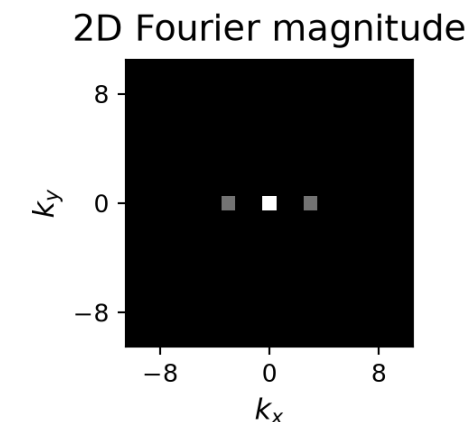
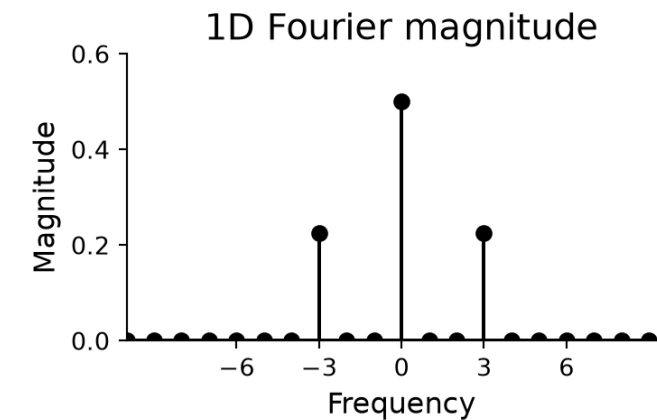
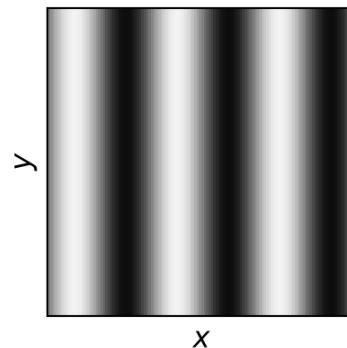
- The constant contributes **one peak at zero frequency**, with magnitude $|c_0|$. It is not split into two peaks.
- For images, the DC component corresponds to the **average pixel intensity**.

A 1D Signal as an Image

Repeat the same 1D intensity signal along every image row.



The same signal in every row



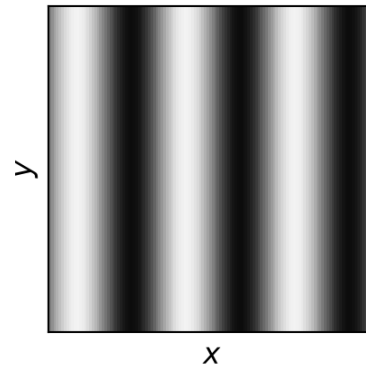
What do the three bright spots represent?

- **Center:** the mean image intensity.
- **Side pair:** the sinusoidal variation along x . Every row is identical, so there is no variation along y .

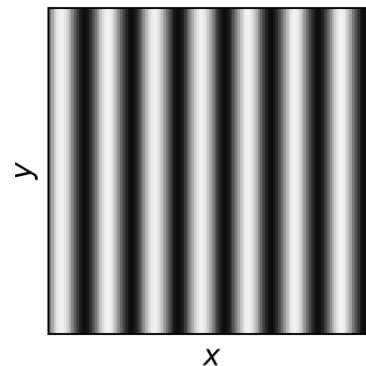
Stripe Spacing and Frequency

What changes when the stripes become **narrower**?

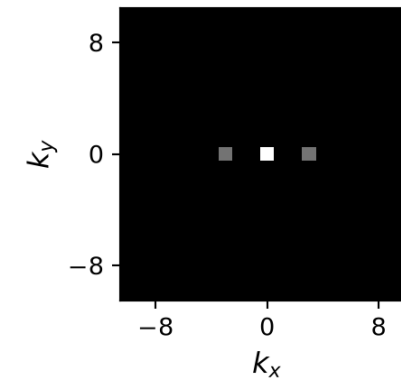
3 cycles across the image



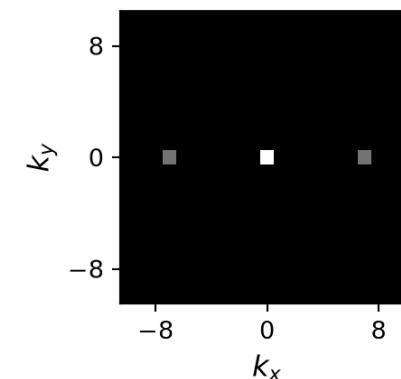
7 cycles across the image



Peaks closer to the center



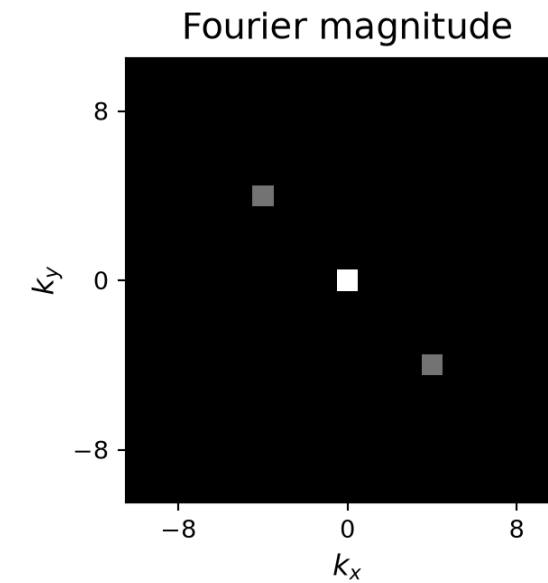
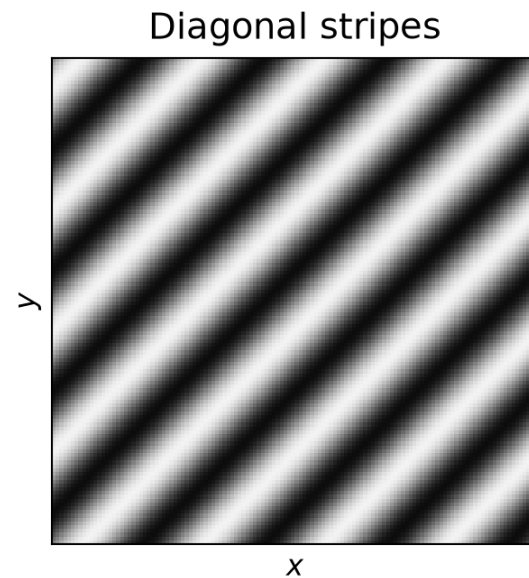
Peaks farther from the center



- Narrower stripes mean **higher spatial frequency**.
- The side peaks move **farther from the center**.
- The center spot stays the same because the mean intensity is unchanged.

Diagonal Stripes

Does the Fourier intensity change along x , along y , or both?

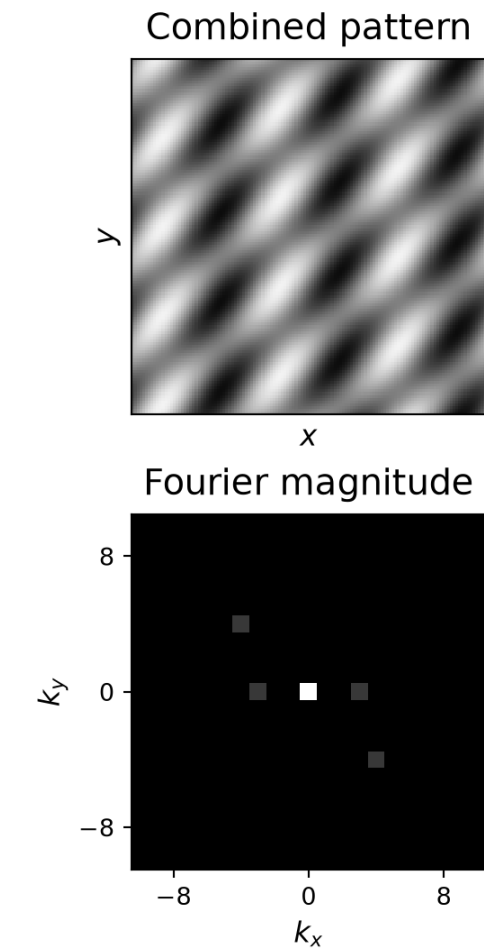
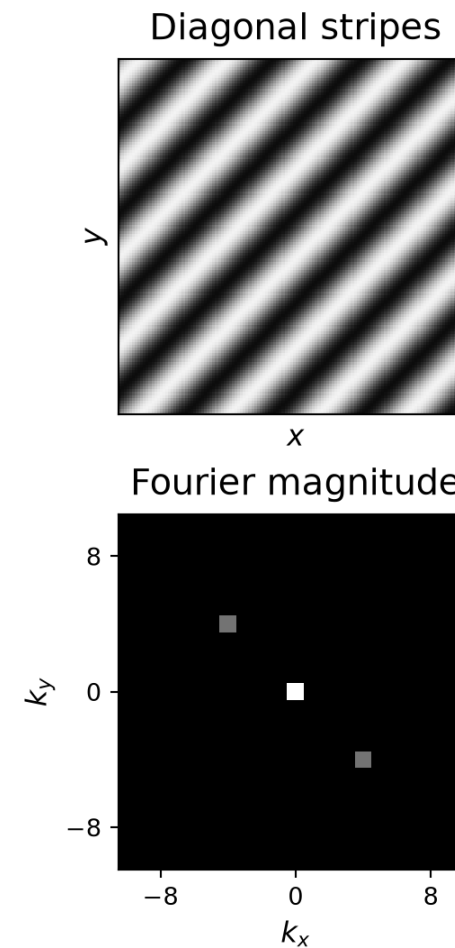
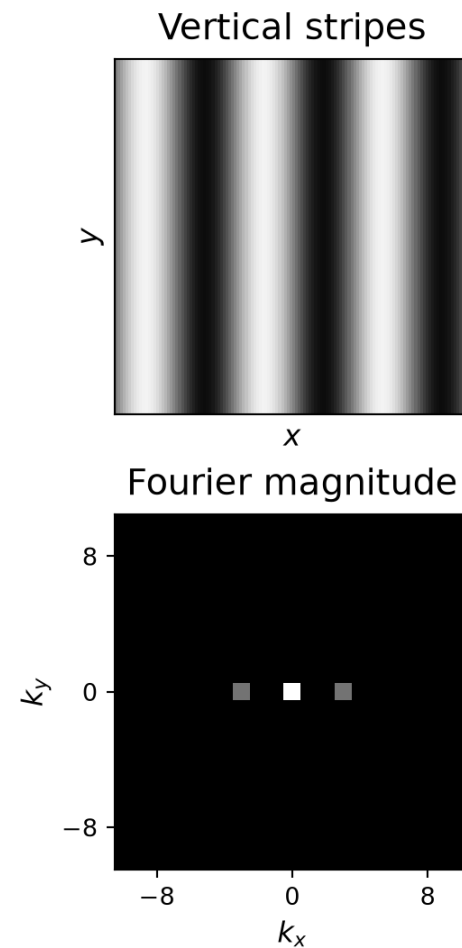


Both. The sinusoid varies along a diagonal direction.

- Its frequency has both **horizontal and vertical components**.
- The two side peaks lie off the horizontal and vertical axes.
- The line joining the two side peaks is **perpendicular to the stripes**.

Combining Patterns

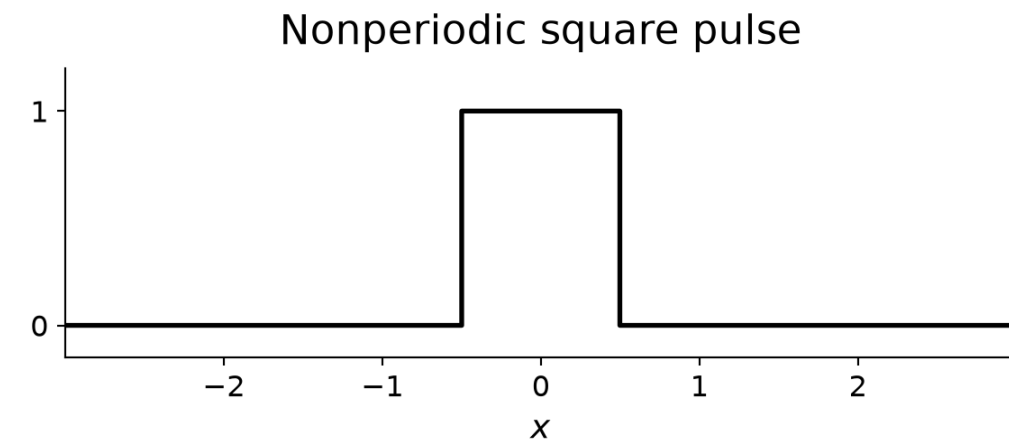
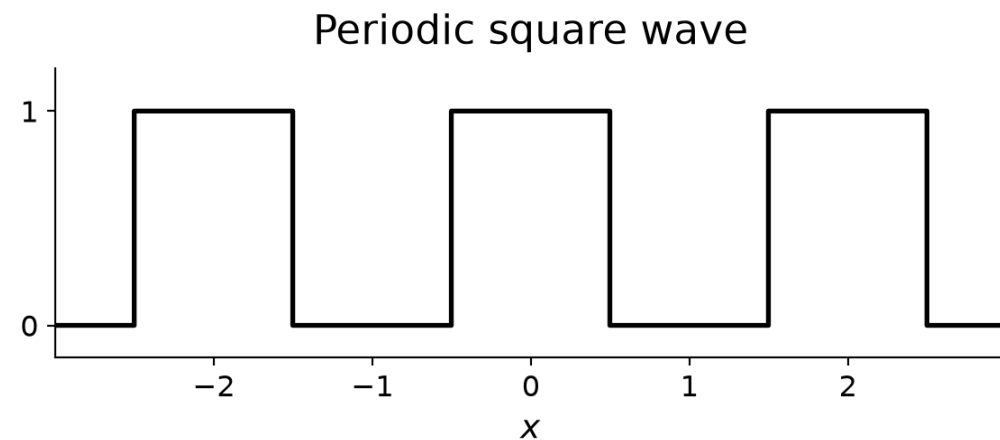
What happens when we **average** these two images?



- **Both peaks** appear in the combined spectrum.
- Averaging halves each pattern's contribution, so its side peaks become dimmer.
- The center spot stays the same because both images have the same mean intensity.

What About Nonperiodic Signals?

Fourier series represent **periodic signals** as sums of sinusoids.



Fourier series

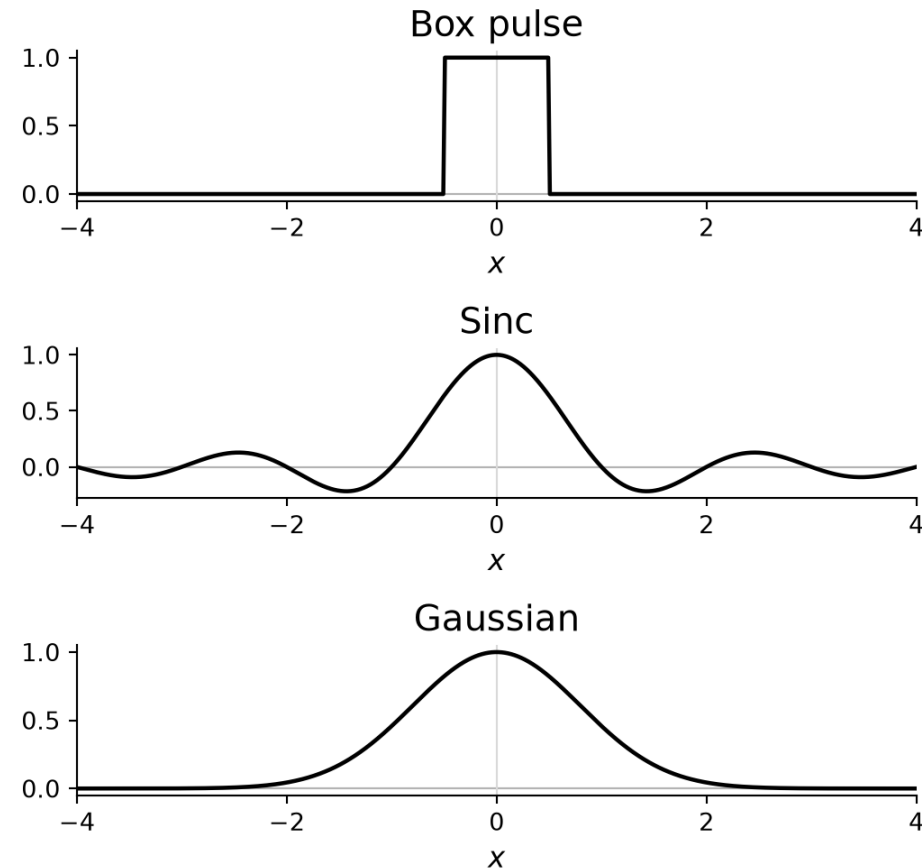
- Signal pattern repeats with period T .
- Uses a **discrete set of frequencies**.

How can we represent a signal that does not repeat?

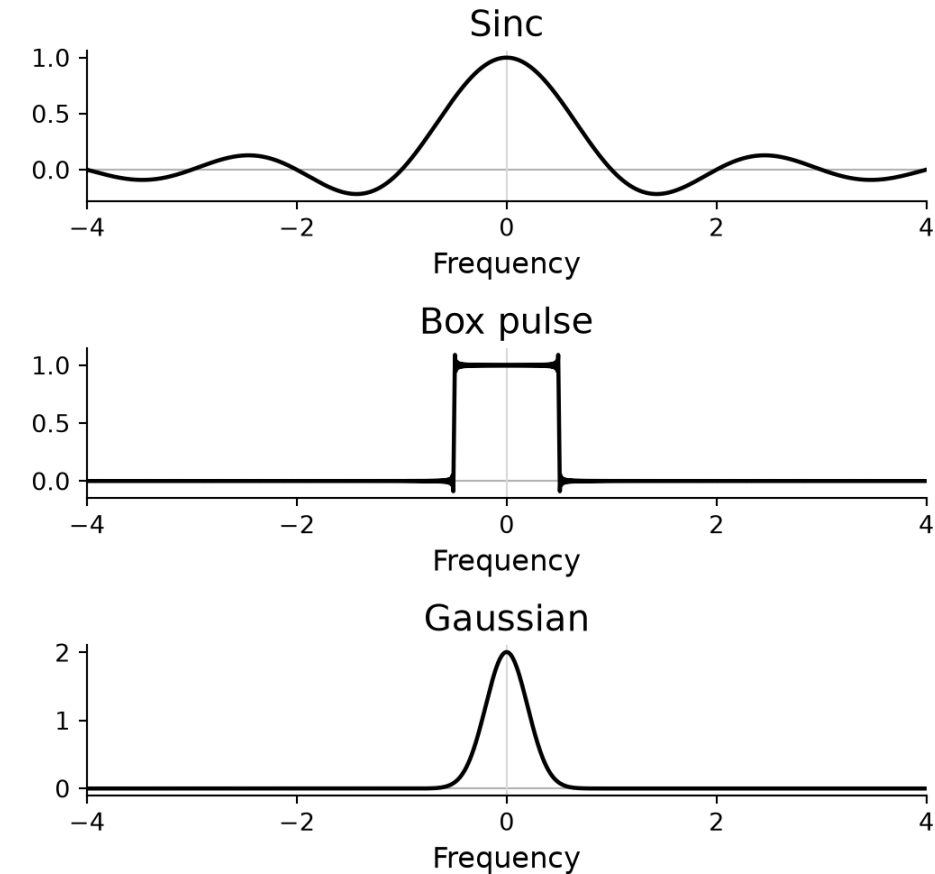
- **Fourier transform:** Extends the idea to nonperiodic signals, allowing a **continuous range of frequencies**.

Fourier Transform Pairs

Spatial domain: $f(x)$



Frequency domain: $\text{Re}\{F(\nu)\}$



- Box $\leftrightarrow$ sinc: an example of Fourier-transform **duality**.
- A Gaussian transforms into another Gaussian; a broader Gaussian produces a narrower spectrum.

Complex Numbers: Cartesian Form

A complex number has two parts:

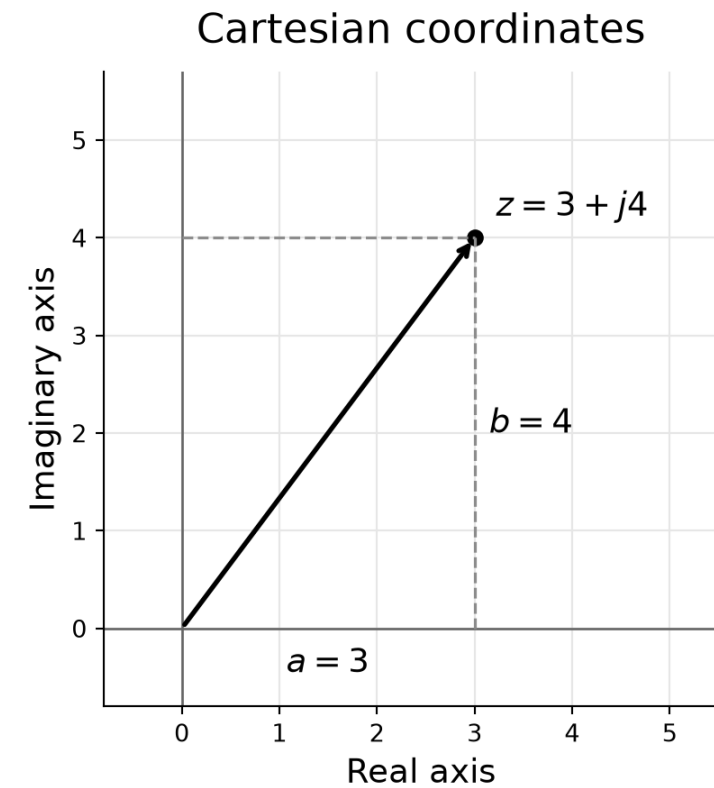
$$z = a + jb, \quad j^2 = -1$$

- a : real part.
- b : imaginary part.

For example:

$$z = 3 + j4$$

The point has coordinates $(a, b) = (3, 4)$ in the **complex plane**.



Complex Numbers: Polar Form

Describe the same point using its **distance and angle**:

$$z = r(\cos \theta + j \sin \theta)$$

How do we compute r and θ ?

$$r = |z| = \sqrt{a^2 + b^2}$$

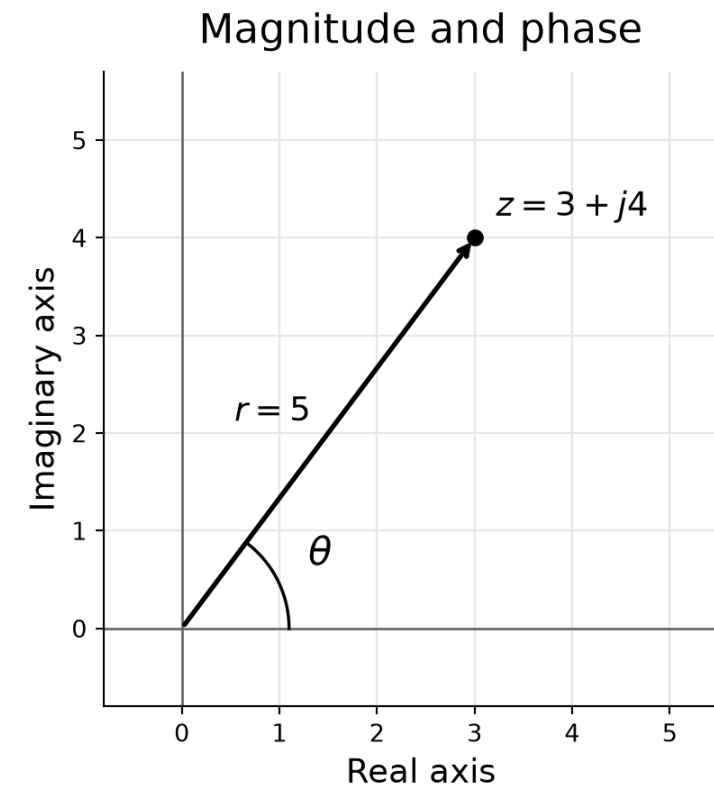
$$\theta = \text{atan2}(b, a)$$

`atan2` accounts for the correct quadrant.

For $z = 3 + j4$:

$$r = 5, \quad \theta \approx 53.13^\circ$$

Same complex number, different coordinates: (a, b) or (r, θ) .



Complex Numbers: Exponential Form

Euler's formula:

$$e^{j\theta} = \cos \theta + j \sin \theta$$

Therefore:

$$z = r(\cos \theta + j \sin \theta) = re^{j\theta}$$

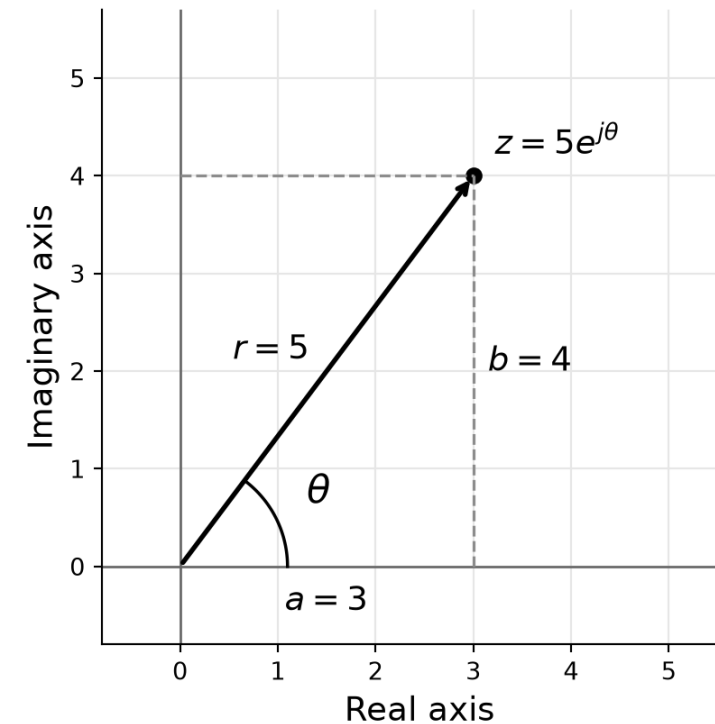
- r : magnitude.
- θ : phase.

For our example, $\theta \approx 0.9273$ radians:

$$3 + j4 \approx 5e^{j0.9273}$$

Euler's formula lets us express the sine and cosine components of the **Fourier transform** using **complex exponentials**.

The same point in exponential form



The Discrete Fourier Transform

For a sampled signal $f[n]$ containing N samples:

Discrete Fourier transform (DFT)

$$F[k] = \frac{1}{N} \sum_{n=0}^{N-1} f[n] e^{-j2\pi kn/N}$$

Inverse DFT

$$f[n] = \sum_{k=0}^{N-1} F[k] e^{j2\pi kn/N}$$

- $n = 0, \dots, N - 1$: sample index.
- $k = 0, \dots, N - 1$: frequency-bin index.
- Continuous spectrum becomes **finite sums**.

Where is the connection to our “ $f[n]$ is a sum of sine waves” idea?

The Inverse Transform Adds Waves

Recall Euler's formula:

$$e^{j\theta} = \cos \theta + j \sin \theta$$

Substitute it into the inverse DFT:

$$f[n] = \sum_{k=0}^{N-1} F[k] e^{j2\pi kn/N} = \sum_{k=0}^{N-1} F[k] \left[\cos\left(\frac{2\pi kn}{N}\right) + j \sin\left(\frac{2\pi kn}{N}\right) \right]$$

- The **sines and cosines** are the wave components.
- Each complex coefficient $F[k]$ determines the component's magnitude and phase.
- The sum over k combines all frequency components.
- For a real-valued signal, matching positive and negative frequencies combine so that the imaginary parts cancel.

The 2D DFT and Its Inverse

For an image $I[m, n]$ with M rows and N columns:

Forward: image to frequency coefficients

$$F[v, u] = \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} I[m, n] e^{-j2\pi\left(\frac{vm}{M} + \frac{un}{N}\right)}$$

Image I

0	0	0.5	0
1	0	1	0
2	0	0	0
	0	1	2

DFT F

0	1.5	-0.75 -j1.3	-0.75 +j1.3
1	-j0.87	-0.75 +j0.43	0.75 +j0.43
2	j0.87	0.75 -j0.43	-0.75 -j0.43
	0	1	2

Inverse: frequency coefficients to image

$$I[m, n] = \frac{1}{MN} \sum_{v=0}^{M-1} \sum_{u=0}^{N-1} F[v, u] e^{j2\pi\left(\frac{vm}{M} + \frac{un}{N}\right)}$$

Inverse DFT

0	0	0.5	0
1	0	1	0
2	0	0	0
	0	1	2

- Nine pixel values become nine complex coefficients.
- The inverse recovers exactly the same original pixel values.

The DFT as a Matrix Multiplication

A 1D DFT computes a **weighted sum** for each frequency:

$$F[k] = \sum_{n=0}^{N-1} f[n] \underbrace{e^{-j2\pi kn/N}}_{\text{weight for sample } n}$$

Collect these weights into a matrix:

$$W_N[k, n] = \omega^{kn}, \quad \omega = e^{-j2\pi/N}$$

$$\begin{bmatrix} F[0] \\ F[1] \\ \vdots \\ F[N-1] \end{bmatrix} = \underbrace{\begin{bmatrix} 1 & 1 & \cdots & 1 \\ 1 & \omega & \cdots & \omega^{N-1} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & \omega^{N-1} & \cdots & \omega^{(N-1)^2} \end{bmatrix}}_{\mathbf{W}_N} \begin{bmatrix} f[0] \\ f[1] \\ \vdots \\ f[N-1] \end{bmatrix}$$

Each row of $\mathbf{W}_N$ computes **one frequency coefficient**:

$$\mathbf{F} = \mathbf{W}_N \mathbf{f}$$

The **FFT** computes this same DFT efficiently, without explicitly building large DFT matrices.

Computing the Image DFT with Matrices

For our 3×3 image, set $N = 3$ in the DFT matrix:

$$\mathbf{W}_3 = \begin{bmatrix} 1 & 1 & 1 \\ 1 & \omega & \omega^2 \\ 1 & \omega^2 & \omega \end{bmatrix}, \quad \omega = e^{-j2\pi/3}$$

Here $\omega^3 = 1$, so $\omega^4 = \omega$.

$$\underbrace{\mathbf{B} = \mathbf{I}\mathbf{W}_3^T}_{\text{Transform each row}}$$

$$\underbrace{\mathbf{F} = \mathbf{W}_3\mathbf{B}}_{\text{Transform each column}}$$

Image I

0	0	0.5	0
1	0	1	0
2	0	0	0
	0	1	2

Rows transformed: B

0	0.5	-0.25 -j0.43	-0.25 +j0.43
1	1	-0.5 -j0.87	-0.5 +j0.87
2	0	0	0
	0	1	2

Columns transformed: F

0	1.5	-0.75 -j1.3	-0.75 +j1.3
1	-j0.87	-0.75 +j0.43	0.75 +j0.43
2	j0.87	0.75 -j0.43	-0.75 -j0.43
	0	1	2

These are the **same Fourier coefficients** as before, computed using row and column transforms.

Magnitude and Phase of the Same Transform

At each frequency, the same coefficient has two representations:

Cartesian form:

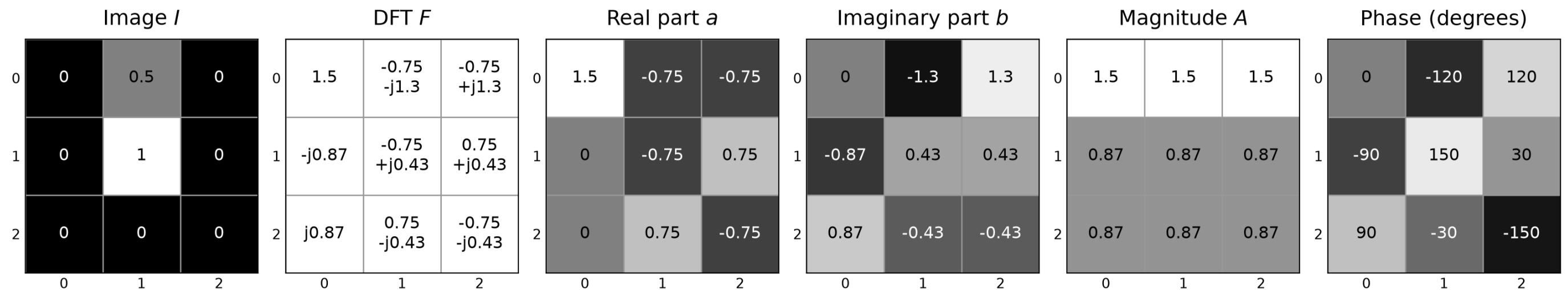
$$F = a + jb$$

- Real part: $a = \text{Re}\{F\}$.
- Imaginary part: $b = \text{Im}\{F\}$.

Polar form:

$$F = Ae^{j\theta}$$

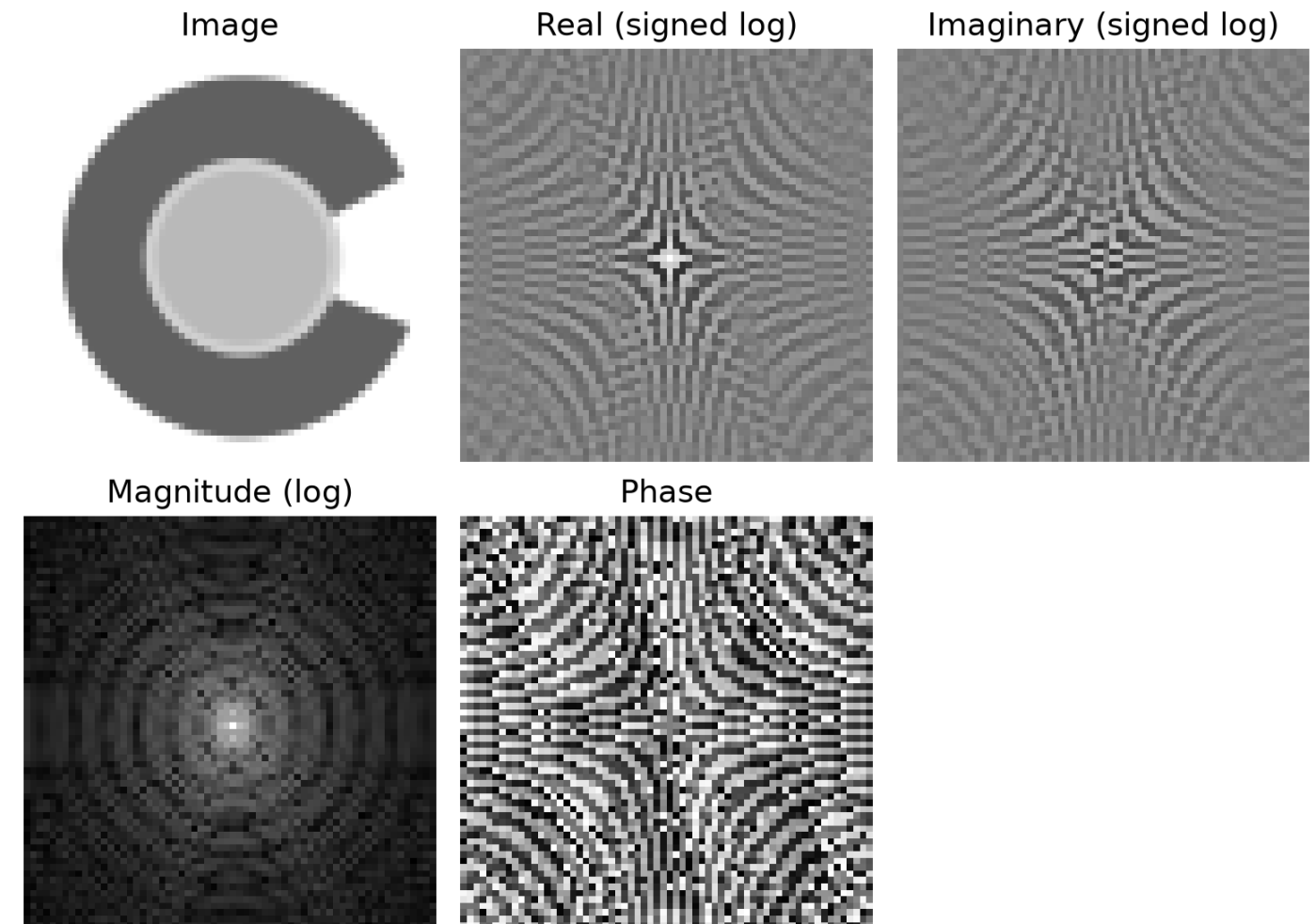
- Magnitude: $A = |F| = \sqrt{a^2 + b^2}$.
- Phase: $\theta = \text{atan2}(b, a)$.



Magnitude and phase together retain the information needed for reconstruction.

Computing an Image DFT with OpenCV

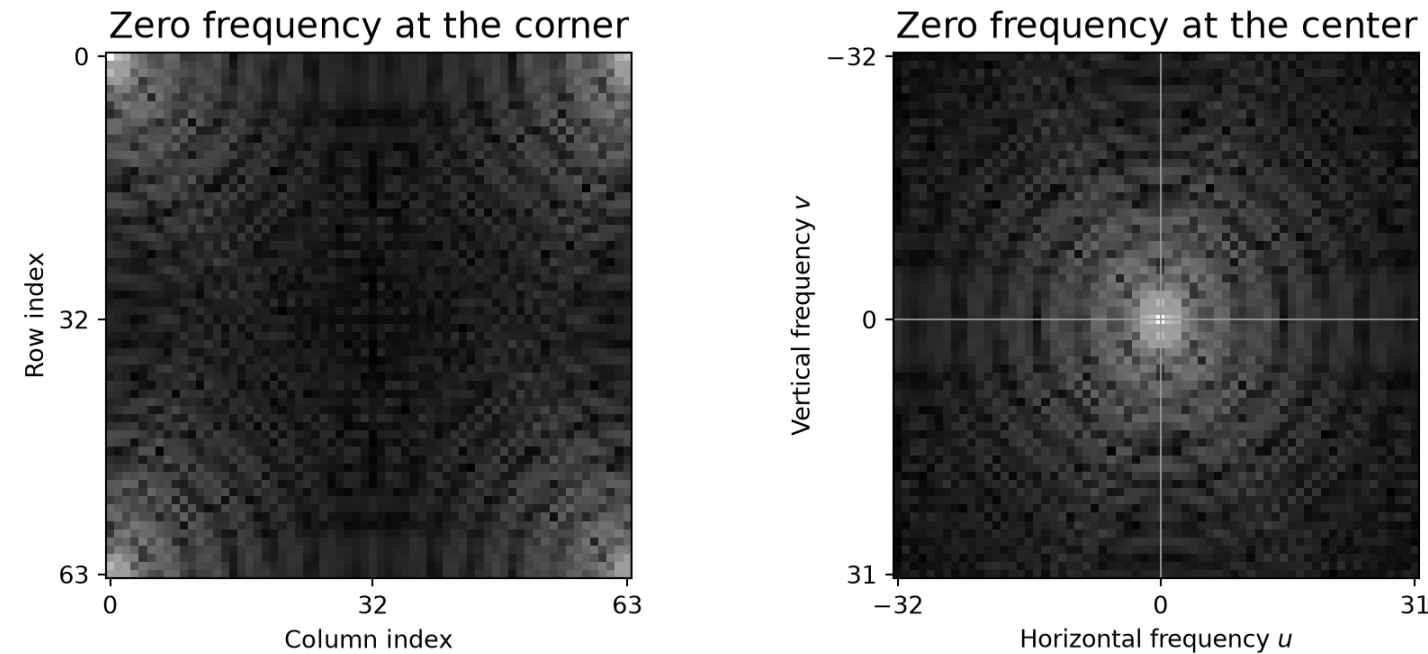
```
1 import cv2
2 import numpy as np
3 import matplotlib.pyplot as plt
4
5 I = cv2.imread("assets/05_fourier_transform/05_c.png",
6               cv2.IMREAD_GRAYSCALE)
7
8 I = cv2.resize(I, (64, 64), interpolation=cv2.INTER_LINEAR)
9 I = I.astype(np.float32) / 255
10 H, W = I.shape
11
12 F_raw = cv2.dft(I, flags=cv2.DFT_COMPLEX_OUTPUT)
13 F = np.roll(F_raw, (H//2, W//2), axis=(0, 1))
14
15 a, b = F[:, :, 0], F[:, :, 1]
16 A, theta = cv2.cartToPolar(a, b)
17 theta = np.where(theta > np.pi, theta - 2*np.pi, theta)
18 theta[A == 0] = np.nan
19
20 # Compress contrast for display only.
21 real_view = np.sign(a) * np.log1p(np.abs(a))
22 imag_view = np.sign(b) * np.log1p(np.abs(b))
```



Why Center the Fourier Spectrum?

OpenCV stores the **zero-frequency coefficient** at the **upper-left corner**.

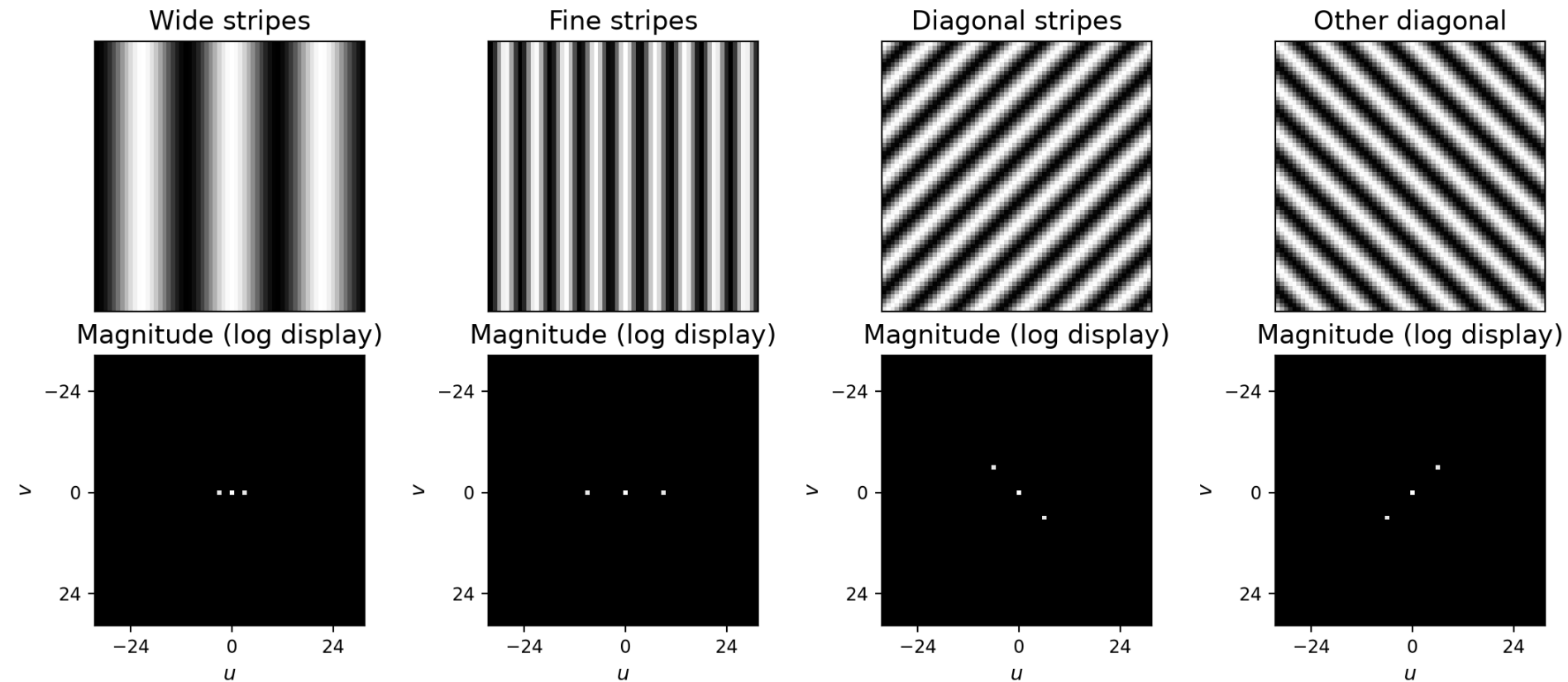
For visualization, **the convention** is to move it to the **center**.



- The center represents **zero frequency**, with positive and negative frequencies on opposite sides.
- Frequencies farther from the center represent **more rapid intensity changes**.
- Centering **rearranges the coefficients**; it does not change their values or the original image's pixel coordinates.

Reading a Fourier Spectrum

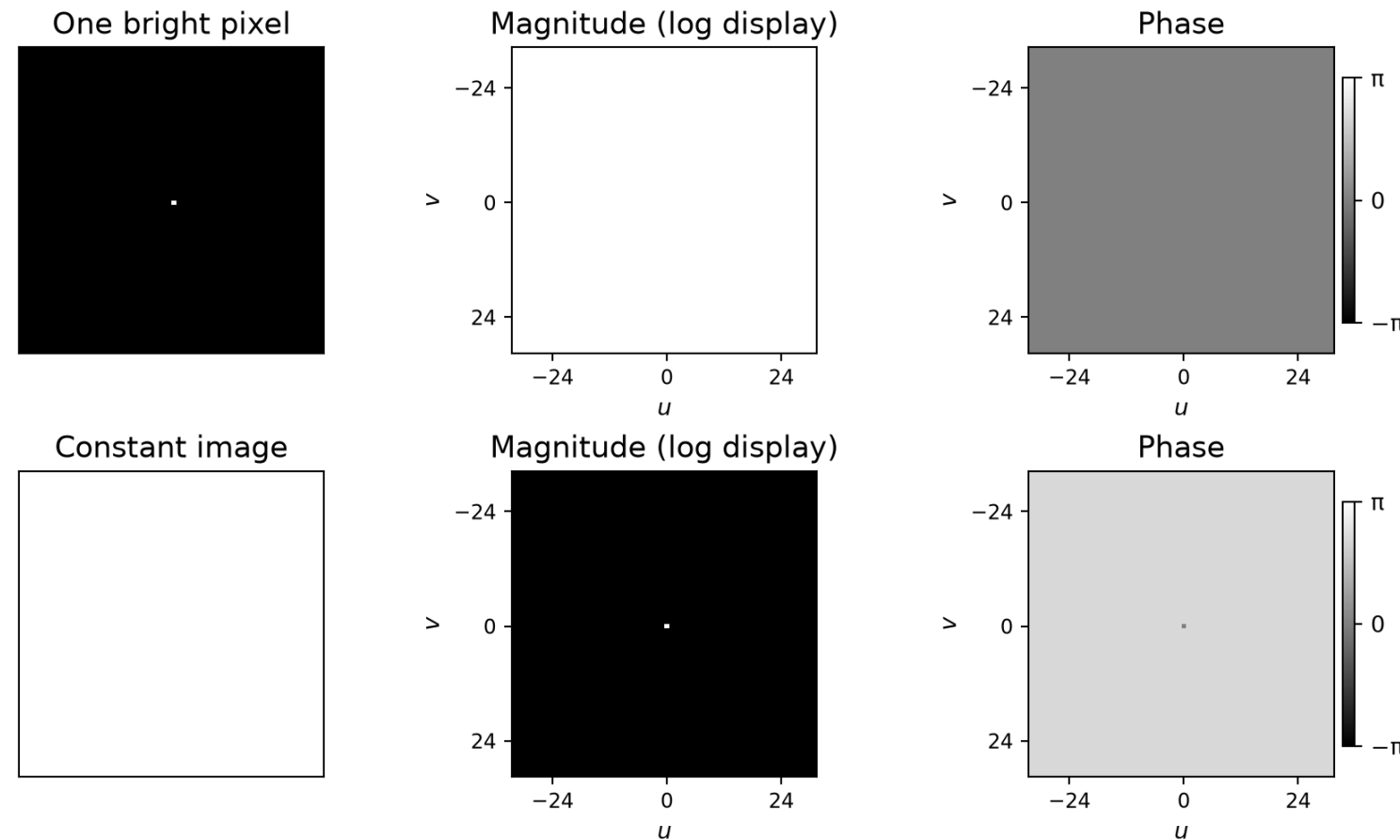
How do these images appear in the spectrum?



- **Finer stripes:** the two side peaks move farther from the center.
- **Orientation:** the line joining the peaks is perpendicular to the stripes.
- **Center peak:** these images have a nonzero mean intensity.

Two Extremes: A Point and a Constant Image

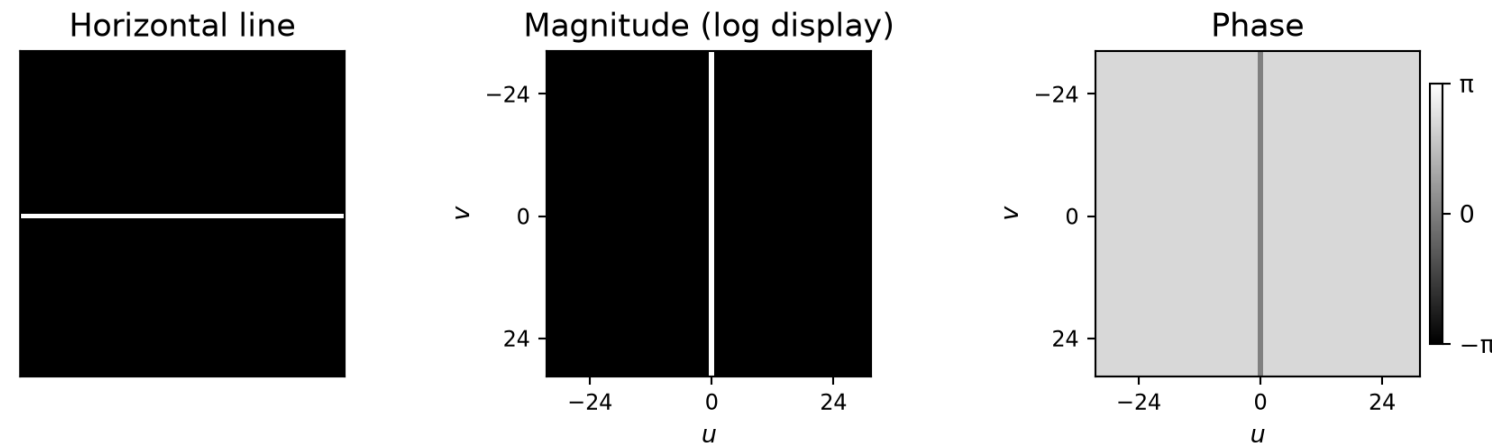
What frequencies are needed to represent each image?



- **One bright pixel:** all frequencies contribute equally; every DFT magnitude is 1.
- **Constant image:** only the zero-frequency component remains; its value is the number of pixels in the image.

From a Point to a Line

A horizontal line is **constant horizontally**, but changes sharply vertically.



Along the line

There is no horizontal variation.

Only the horizontal frequency $u = 0$ is needed.

A horizontal line produces a vertical line in the Fourier magnitude.

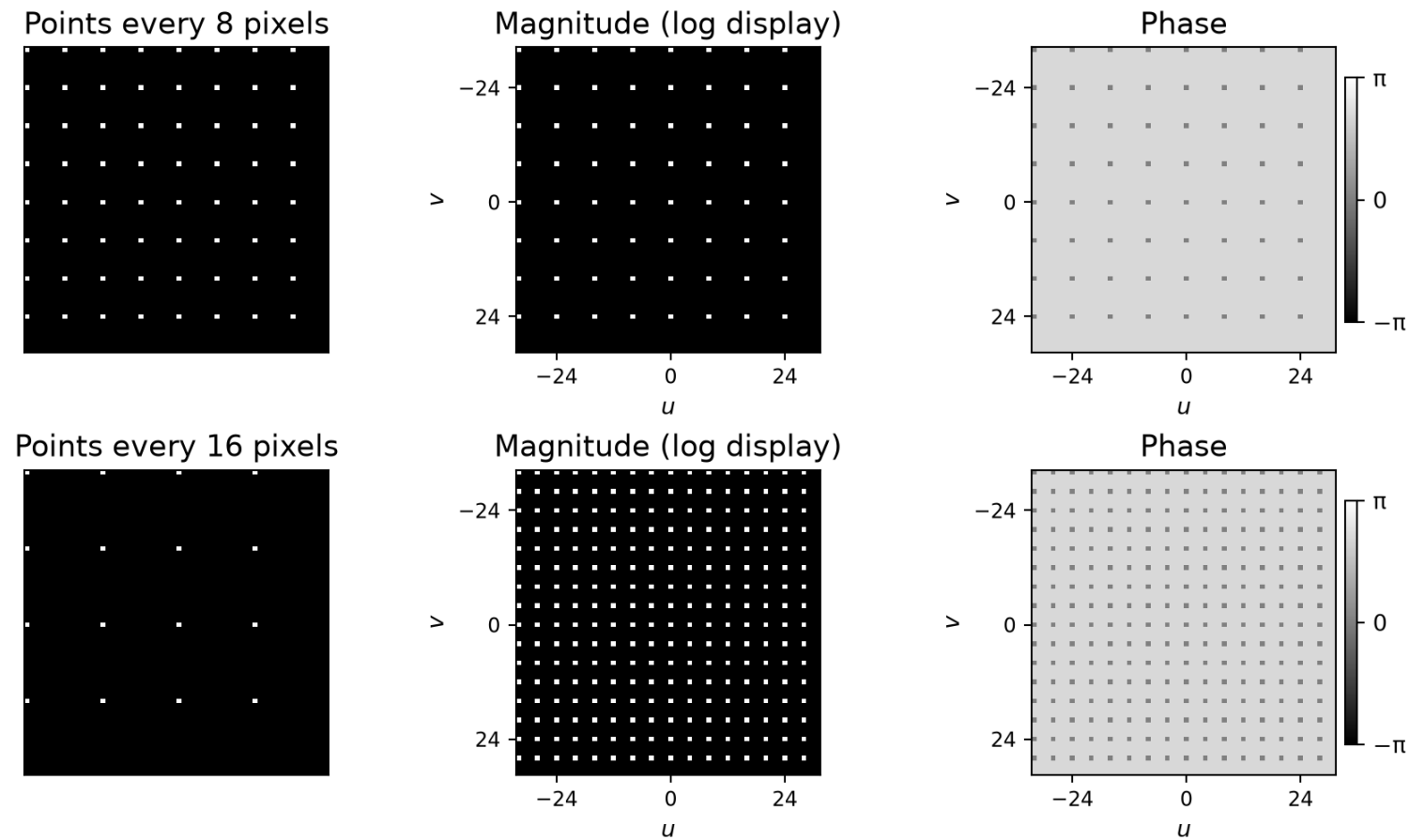
Across the line

A one-pixel change requires all vertical frequencies.

The spectrum extends along the v axis.

Repeated Points Produce Repeated Peaks

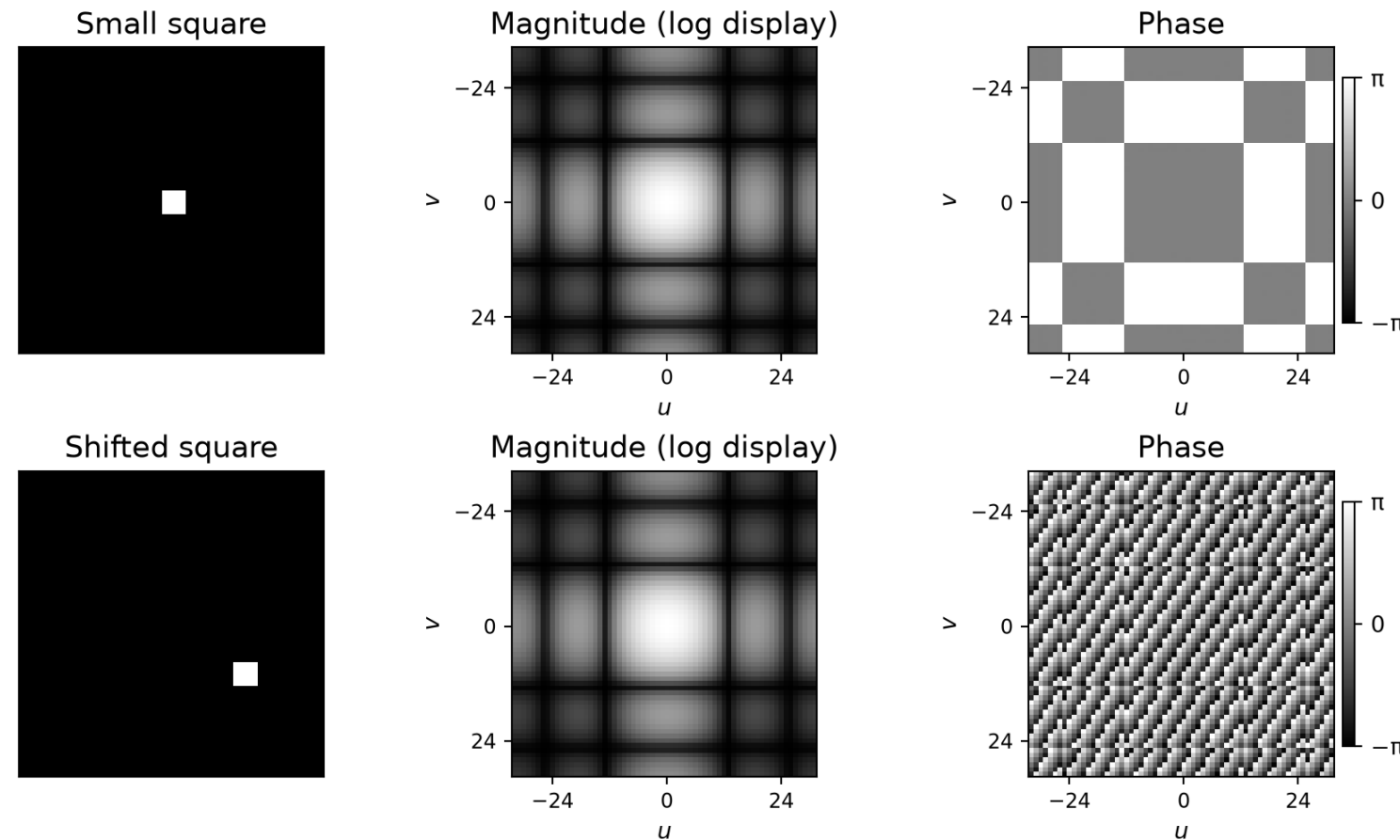
A regular grid of bright pixels is called an **impulse train** or **impulse comb**.



- A regular grid in the image produces a regular grid in the spectrum.
- **Farther-apart points $\rightarrow$ closer-together frequency peaks.**

Translation Changes Phase, Not Magnitude

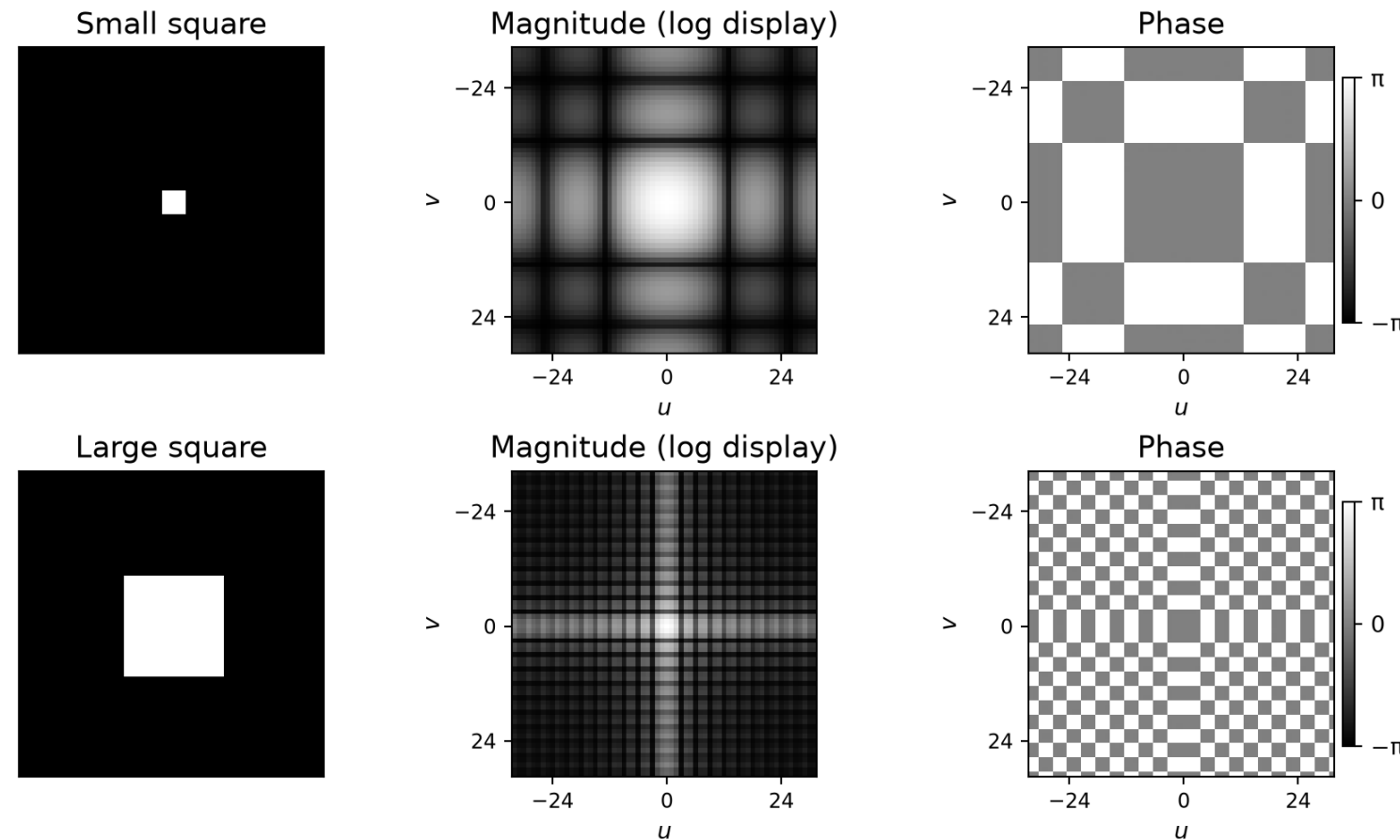
Move the square without changing its shape or brightness.



- The **magnitude stays the same**: the same frequencies are present.
- The **phase changes**: the waves must align at a different location.
- **Magnitude alone cannot tell us where the square is located.**

Spatial Size and Frequency Spread

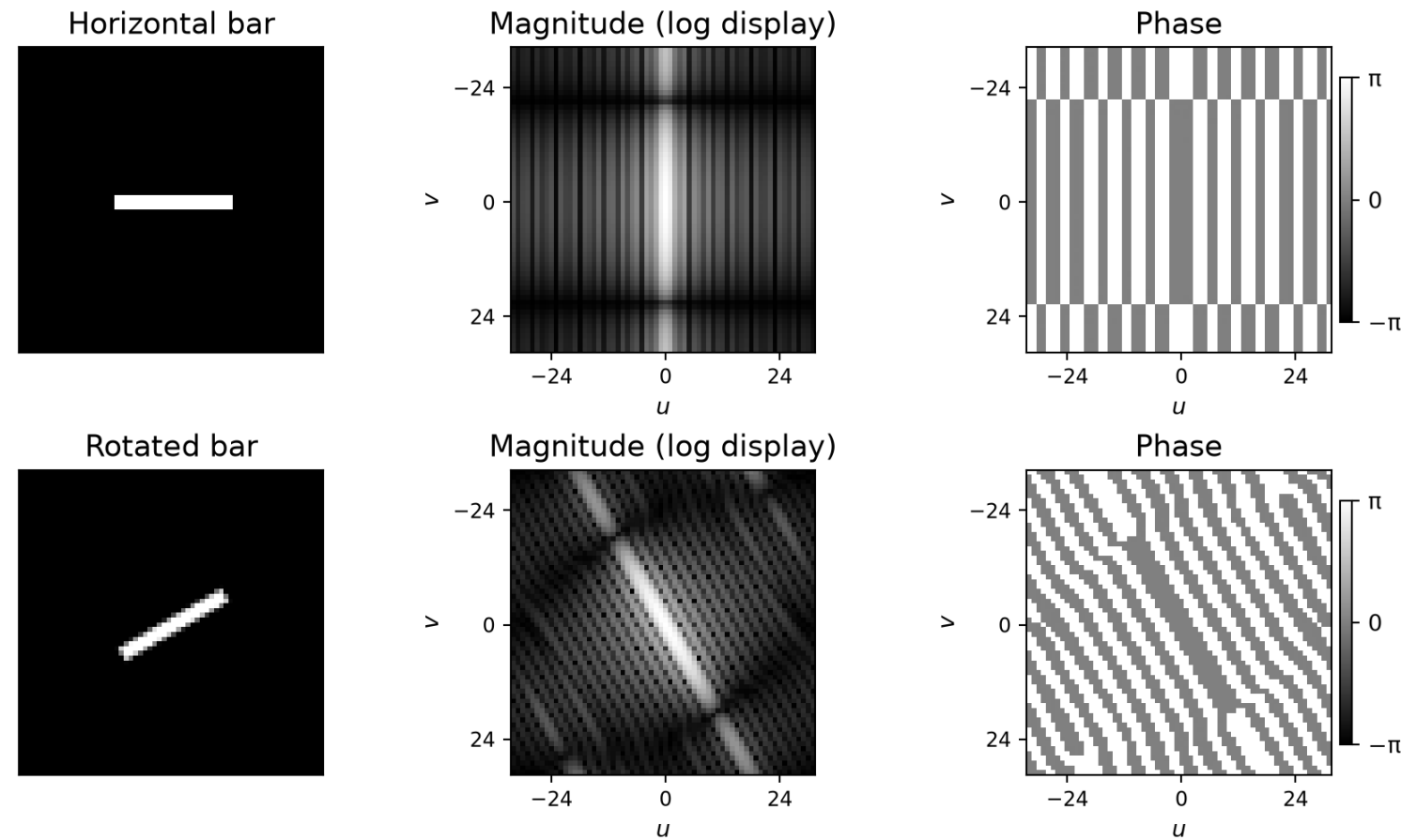
Compare the same shape at two different sizes.



- Smaller square $\rightarrow$ broader central lobe in the spectrum.
- Larger square $\rightarrow$ narrower central lobe.
- Spatial extent and frequency spread have an inverse relationship.

Rotating an Image Rotates Its Spectrum

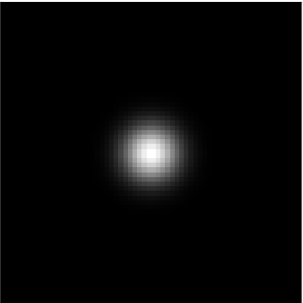
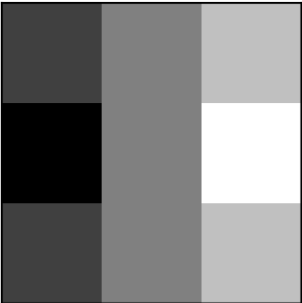
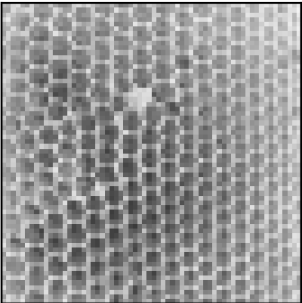
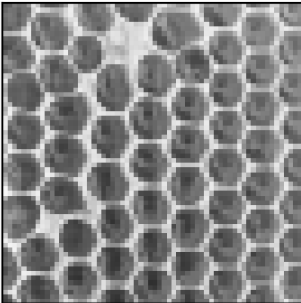
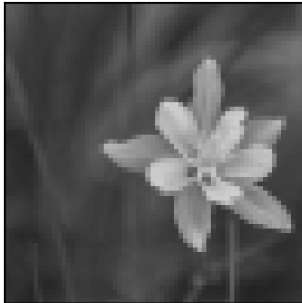
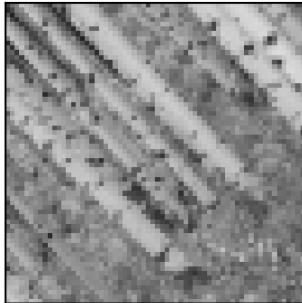
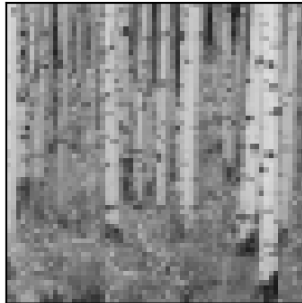
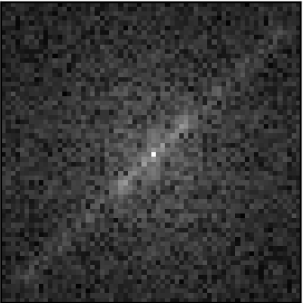
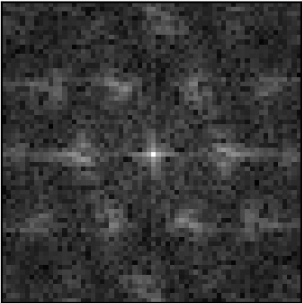
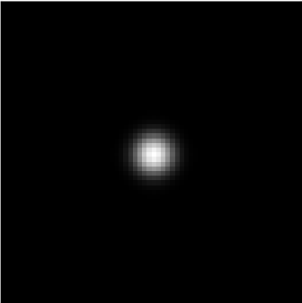
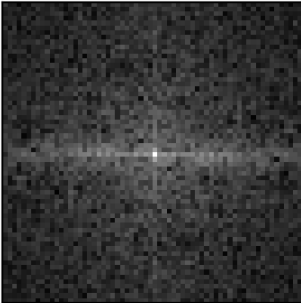
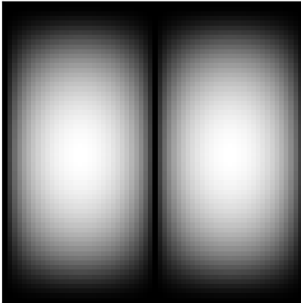
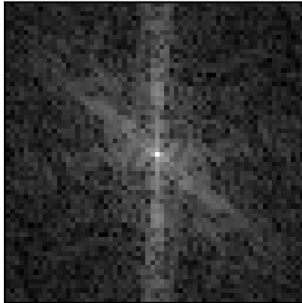
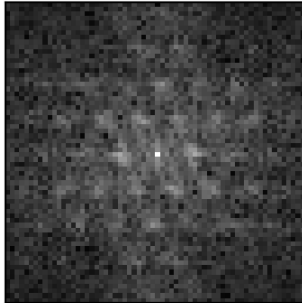
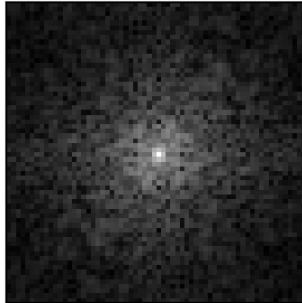
The spectrum follows the orientation of the image.



- Rotating the bar rotates this frequency pattern by the **same angle**.

Quiz: Match Each Image to Its Fourier Spectrum

Match images A–H to the centered DFT amplitudes 1–8.

A	B	C	D	E	F	G	H
							
1	2	3	4	5	6	7	8
							

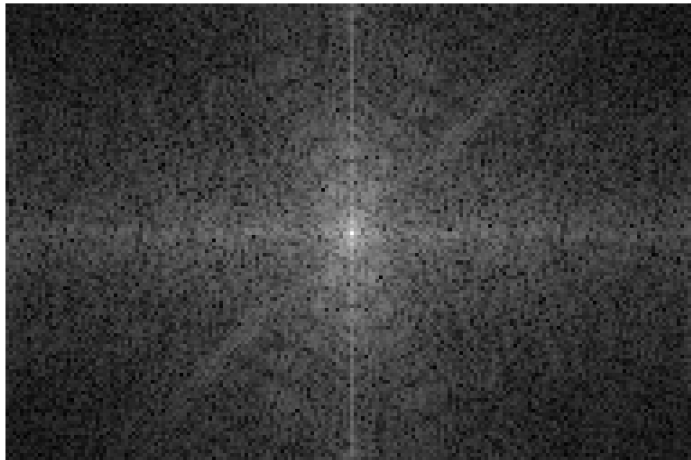
Explain your matches using frequency spread, orientation, and repeated patterns.

Reconstructing an Image from Fourier Coefficients

Original image



Centered DFT amplitude (log display)



The inverse DFT reconstructs the image:

$$I = \mathcal{F}^{-1}(F).$$

What if we retain only **some** coefficients?

1. Keep the selected **complex values**.
2. Set every other coefficient to zero.
3. Apply the inverse DFT.

$$\hat{I}_K = \mathcal{F}^{-1}(M_K \odot F)$$

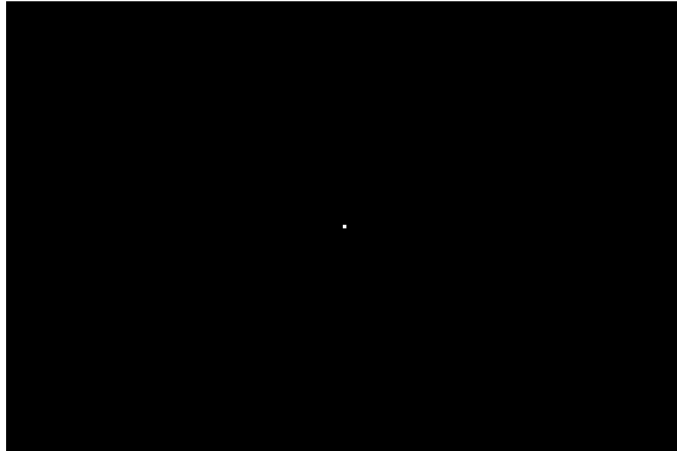
Here, M_K is a binary mask selecting K coefficients.

Which selection works better: random frequencies or frequencies near the center?

Random Selection: 1 Coefficient

1 of 24,257 coefficients (0.00%)

Selected coefficients



Reconstruction



Original



Only **DC** remains: every pixel equals the original image's mean intensity.

White pixels in the mask mark retained coefficients; black pixels mark discarded coefficients.

Random Selection: 9 Coefficients

9 of 24,257 coefficients (0.04%)

Selected coefficients



Reconstruction



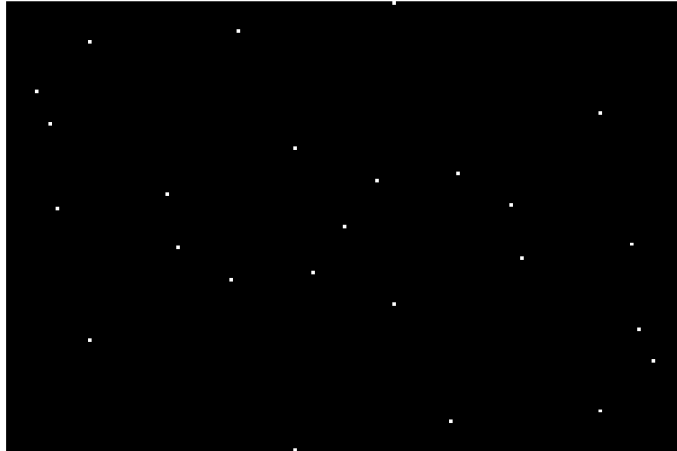
Original



Random Selection: 25 Coefficients

25 of 24,257 coefficients (0.10%)

Selected coefficients



Reconstruction



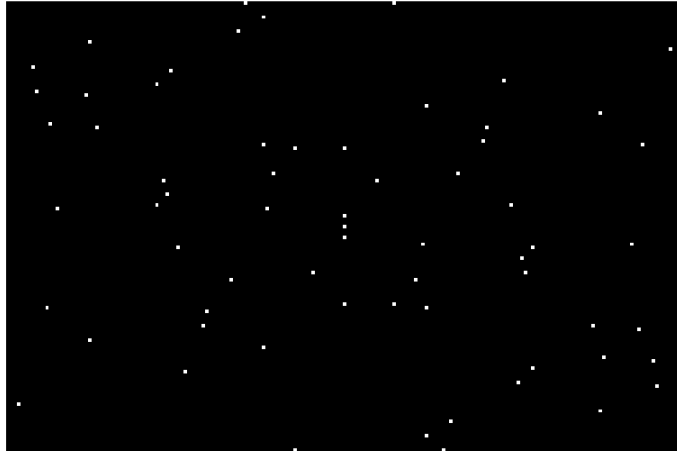
Original



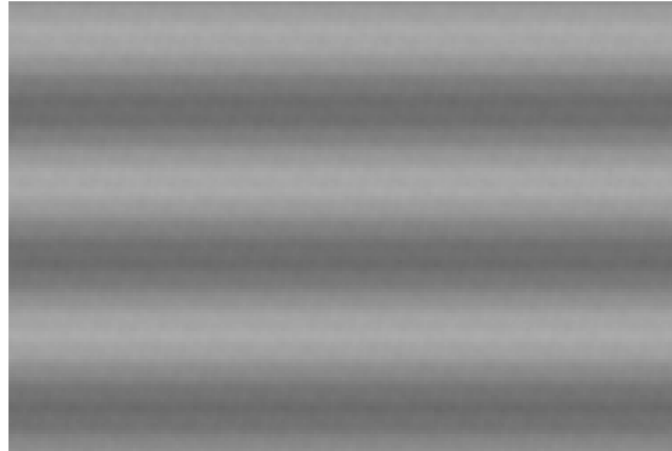
Random Selection: 65 Coefficients

65 of 24,257 coefficients (0.27%)

Selected coefficients



Reconstruction



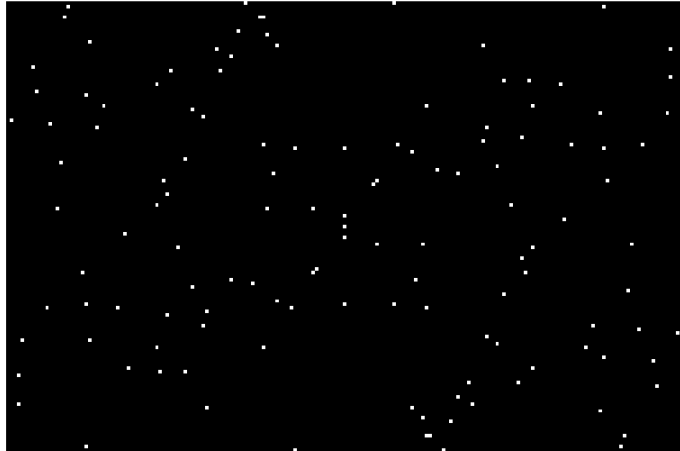
Original



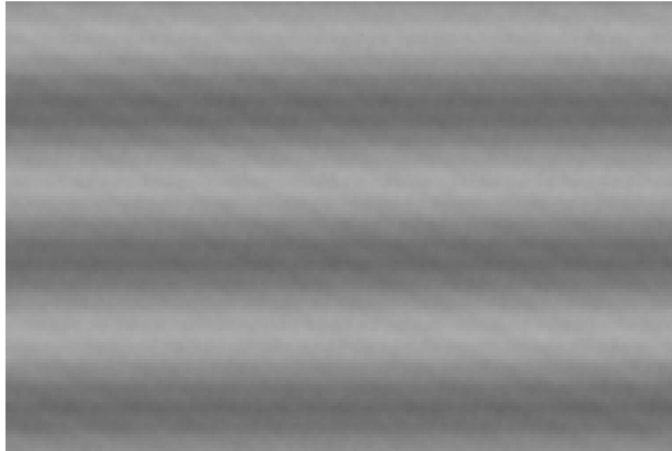
Random Selection: 129 Coefficients

129 of 24,257 coefficients (0.53%)

Selected coefficients



Reconstruction



Original



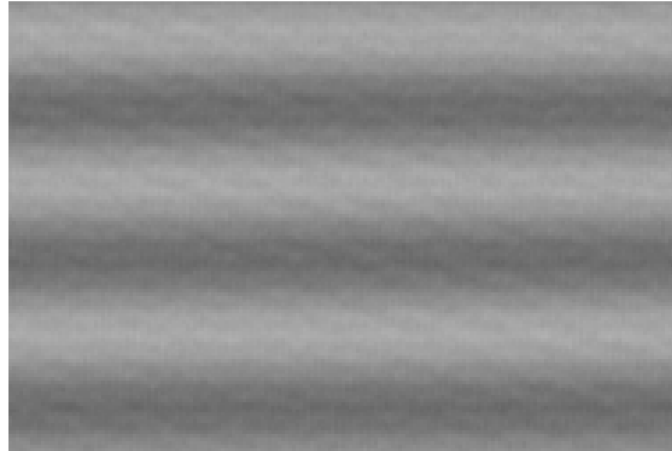
Random Selection: 257 Coefficients

257 of 24,257 coefficients (1.06%)

Selected coefficients



Reconstruction



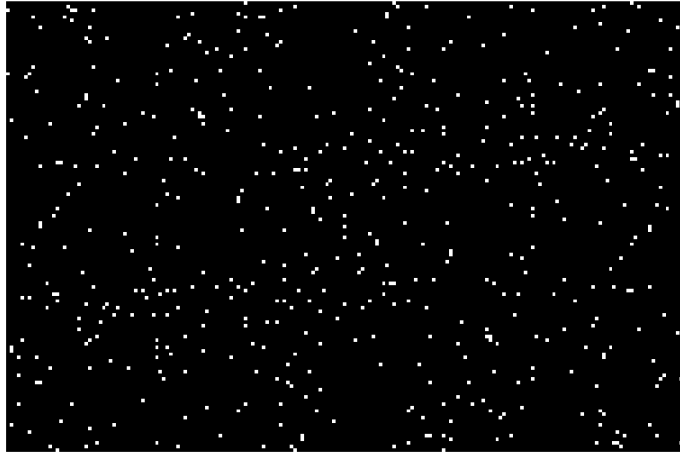
Original



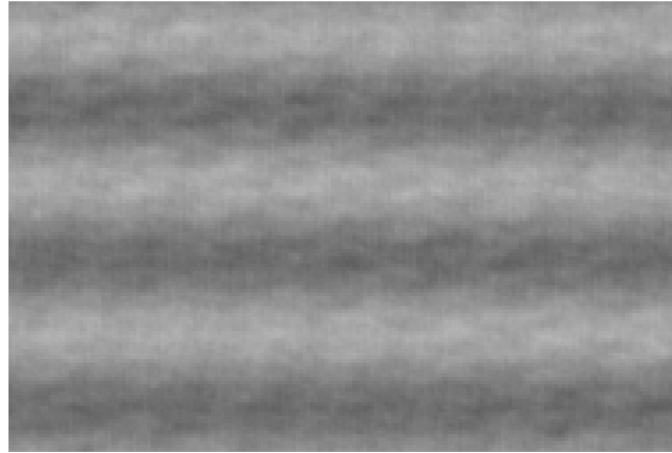
Random Selection: 513 Coefficients

513 of 24,257 coefficients (2.11%)

Selected coefficients



Reconstruction



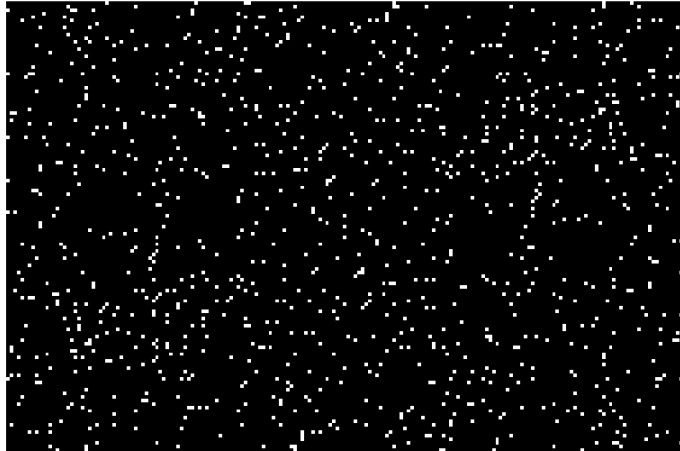
Original



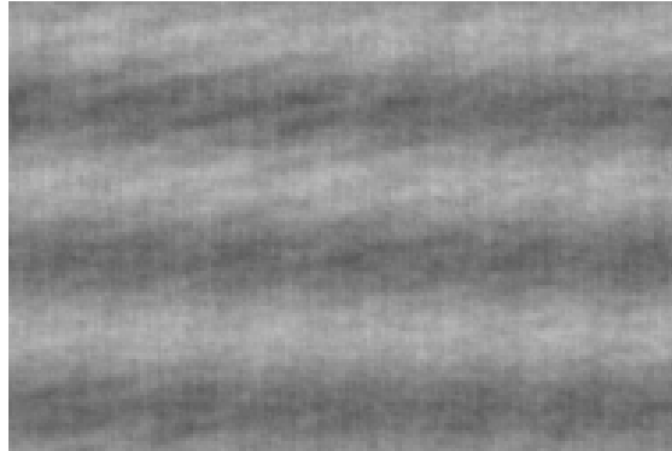
Random Selection: 1,025 Coefficients

1,025 of 24,257 coefficients (4.23%)

Selected coefficients



Reconstruction



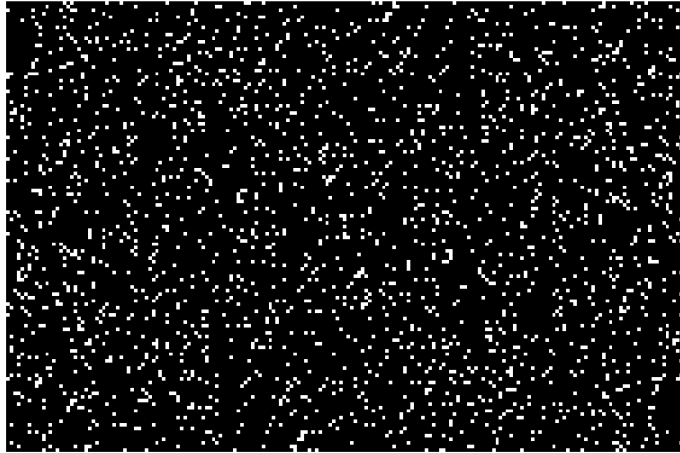
Original



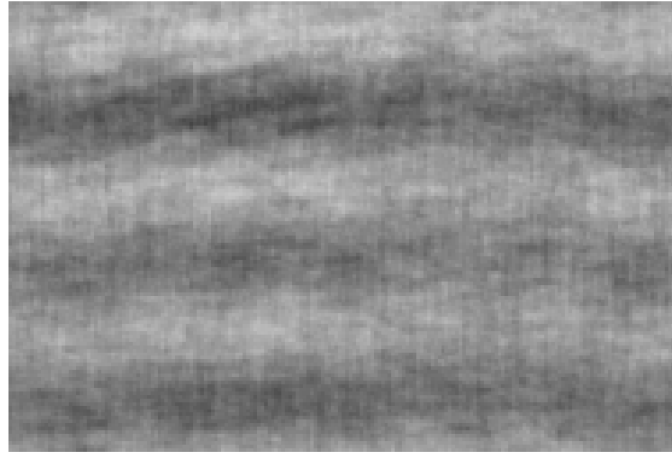
Random Selection: 2,049 Coefficients

2,049 of 24,257 coefficients (8.45%)

Selected coefficients



Reconstruction



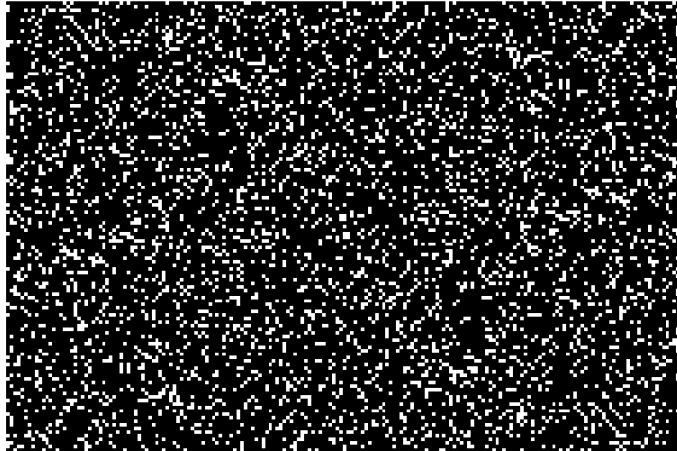
Original



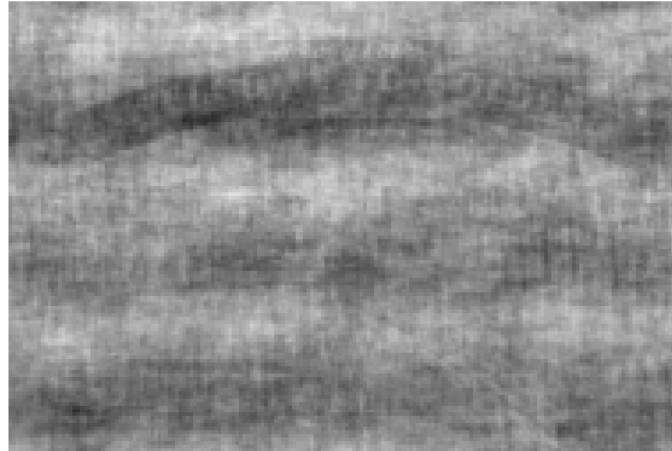
Random Selection: 4,097 Coefficients

4,097 of 24,257 coefficients (16.89%)

Selected coefficients



Reconstruction



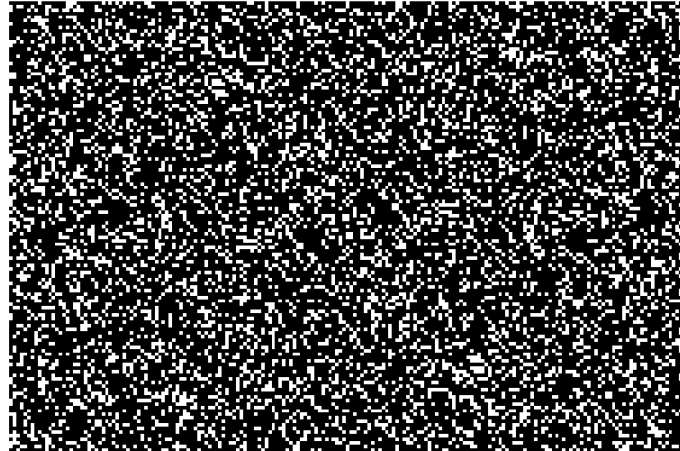
Original



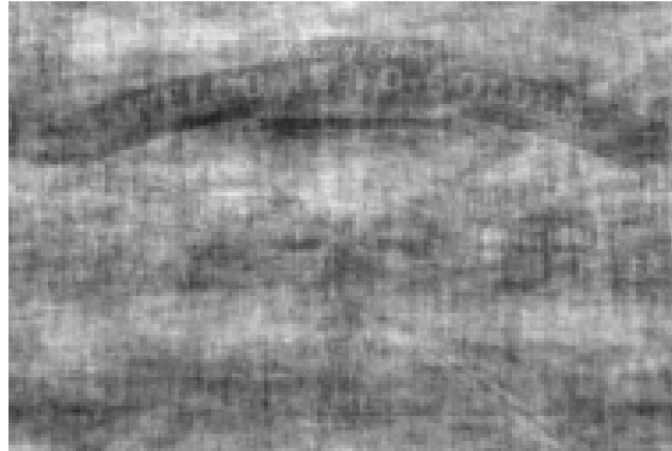
Random Selection: 6,145 Coefficients

6,145 of 24,257 coefficients (25.33%)

Selected coefficients



Reconstruction



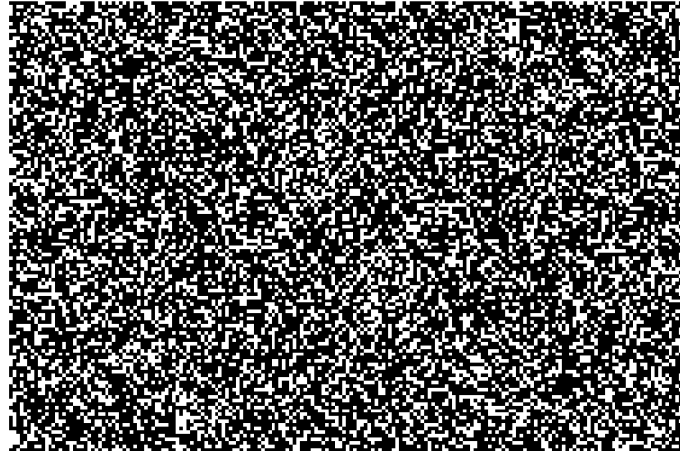
Original



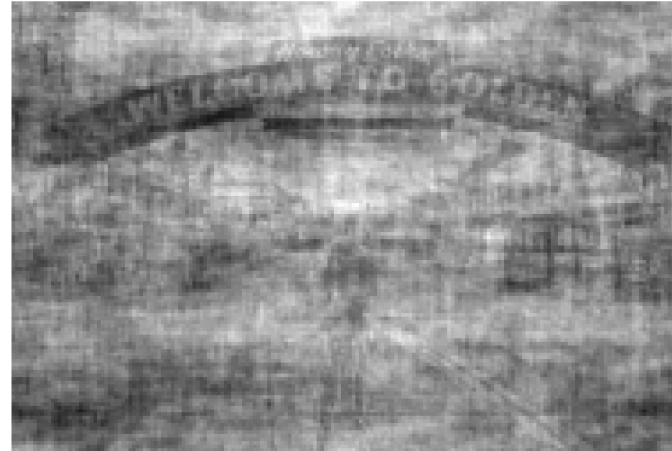
Random Selection: 8,193 Coefficients

8,193 of 24,257 coefficients (33.78%)

Selected coefficients



Reconstruction



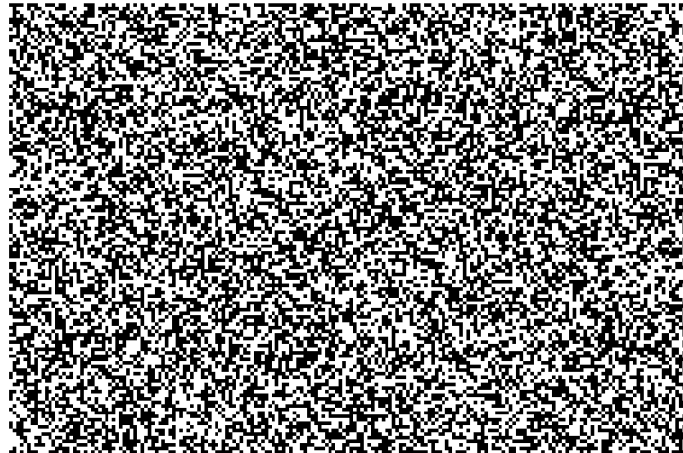
Original



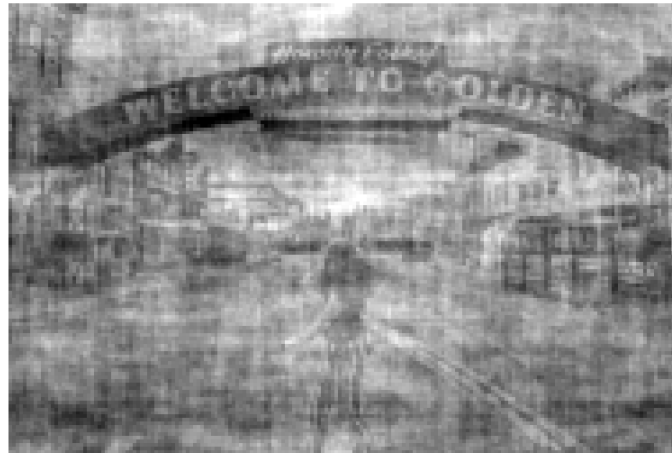
Random Selection: 12,289 Coefficients

12,289 of 24,257 coefficients (50.66%)

Selected coefficients



Reconstruction



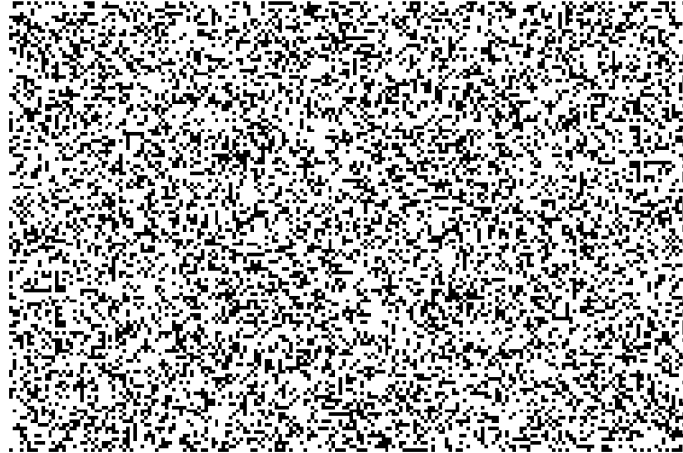
Original



Random Selection: 16,385 Coefficients

16,385 of 24,257 coefficients (67.55%)

Selected coefficients



Reconstruction



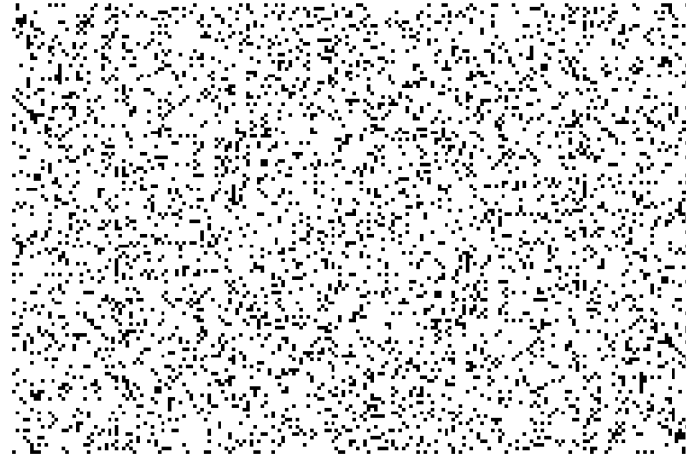
Original



Random Selection: 20,481 Coefficients

20,481 of 24,257 coefficients (84.43%)

Selected coefficients



Reconstruction



Original



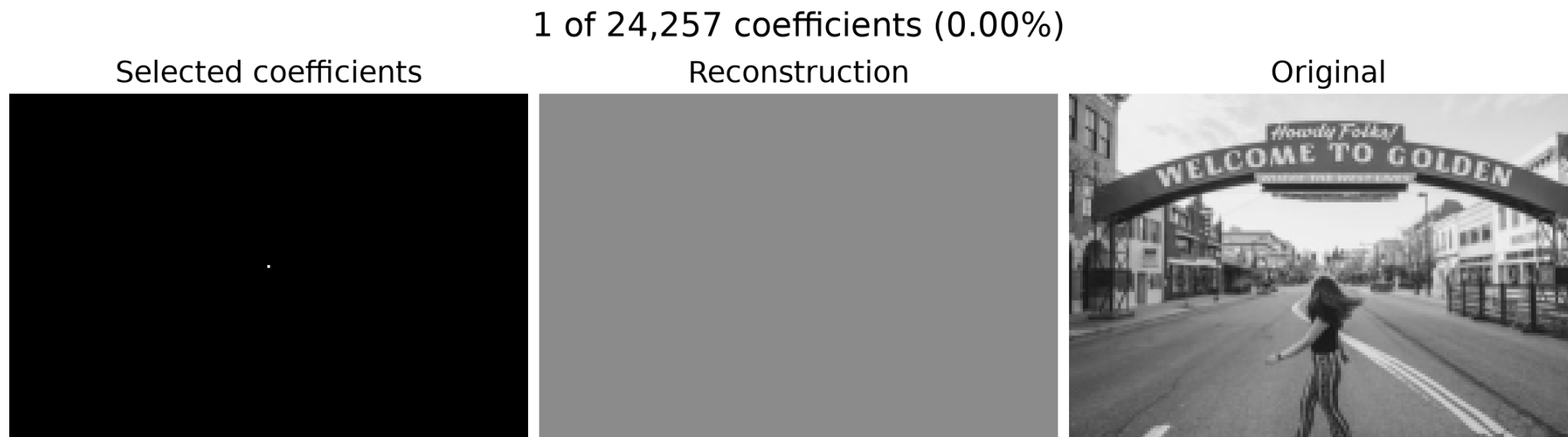
Random Selection: All 24,257 Coefficients



With all coefficients retained, the inverse DFT recovers the original image.

Can we obtain a useful reconstruction with far fewer coefficients?

Selecting from the Center: 1 Coefficient



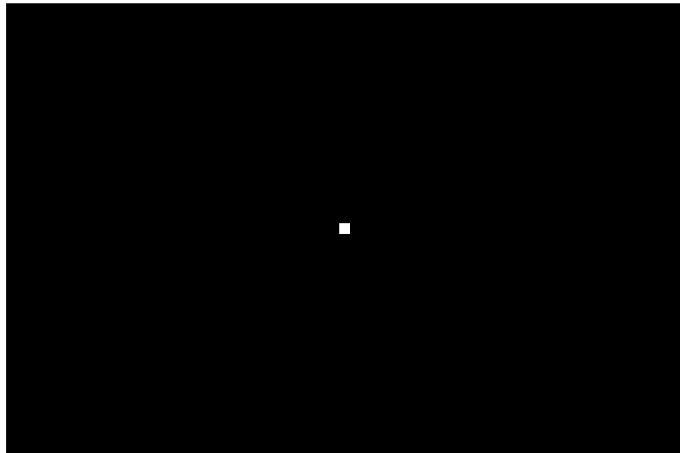
Start with **DC**, then expand outward to include progressively higher frequencies.

We will use **the same coefficient counts** as before.

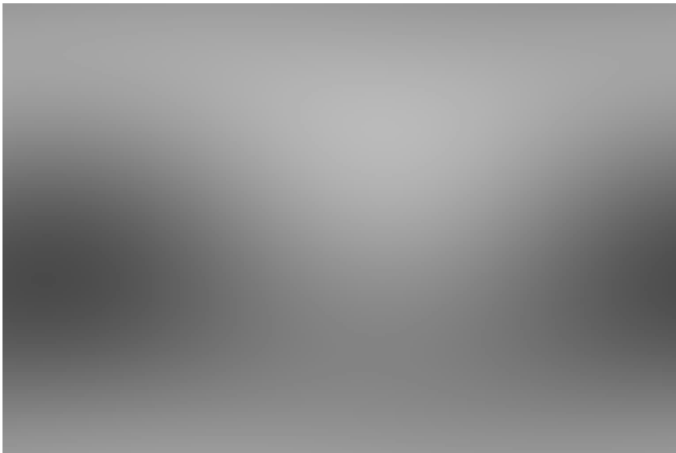
Selecting from the Center: 9 Coefficients

9 of 24,257 coefficients (0.04%)

Selected coefficients



Reconstruction



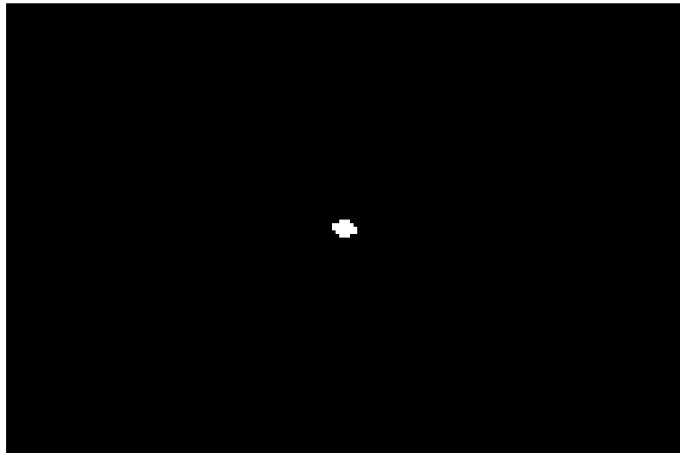
Original



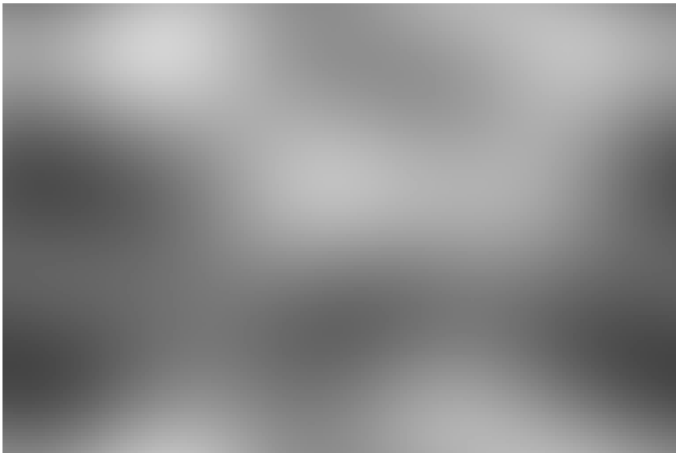
Selecting from the Center: 25 Coefficients

25 of 24,257 coefficients (0.10%)

Selected coefficients



Reconstruction



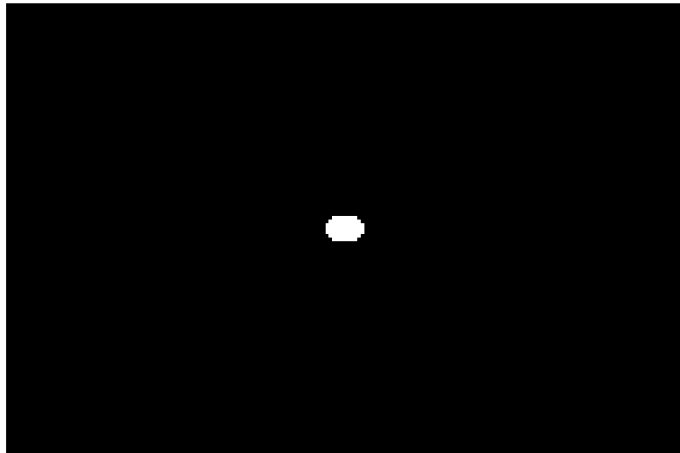
Original



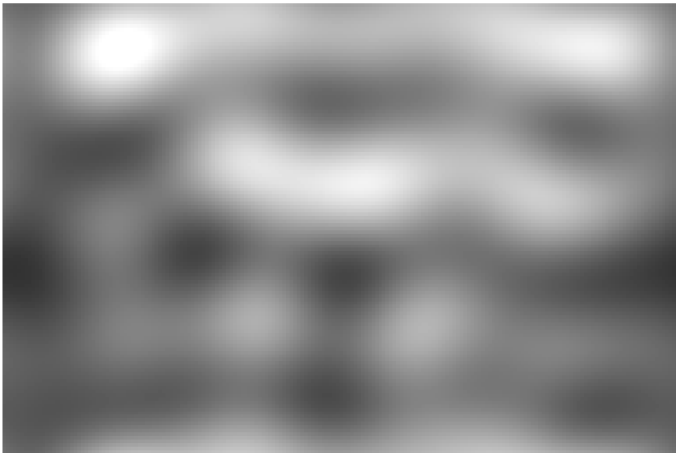
Selecting from the Center: 65 Coefficients

65 of 24,257 coefficients (0.27%)

Selected coefficients



Reconstruction



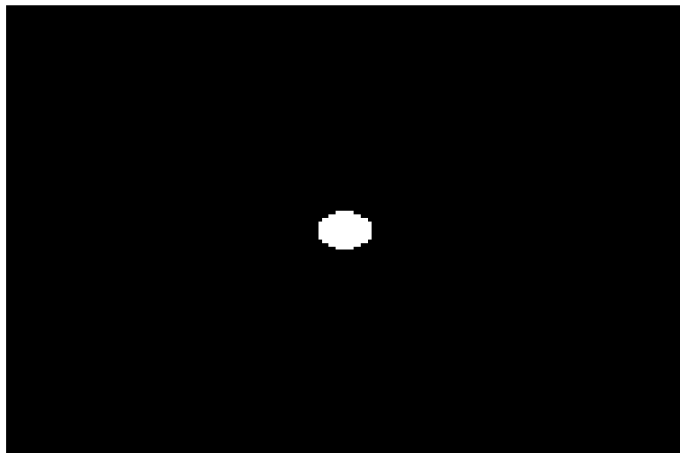
Original



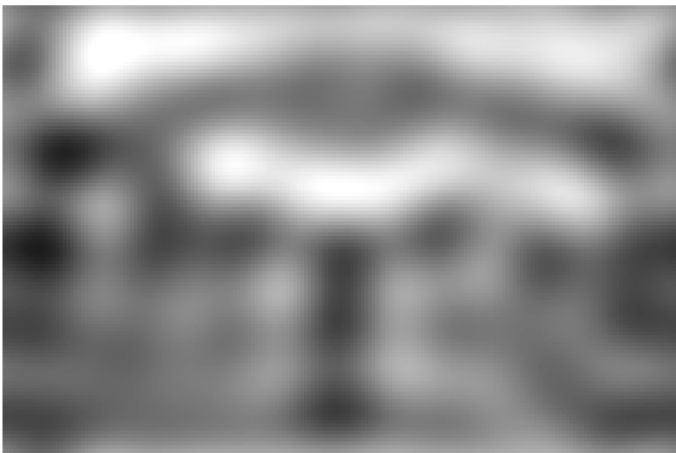
Selecting from the Center: 129 Coefficients

129 of 24,257 coefficients (0.53%)

Selected coefficients



Reconstruction



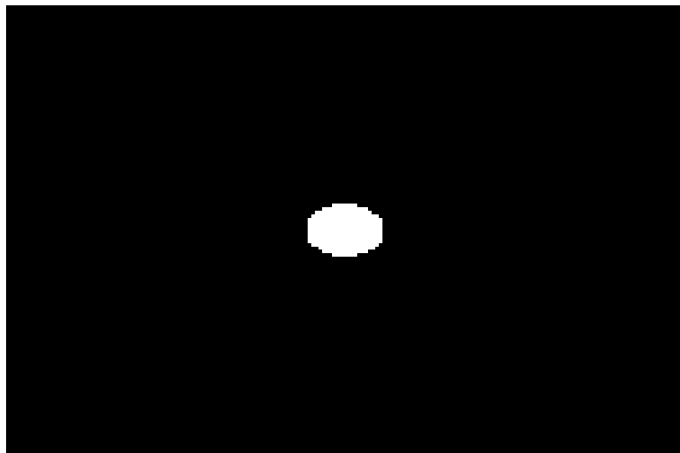
Original



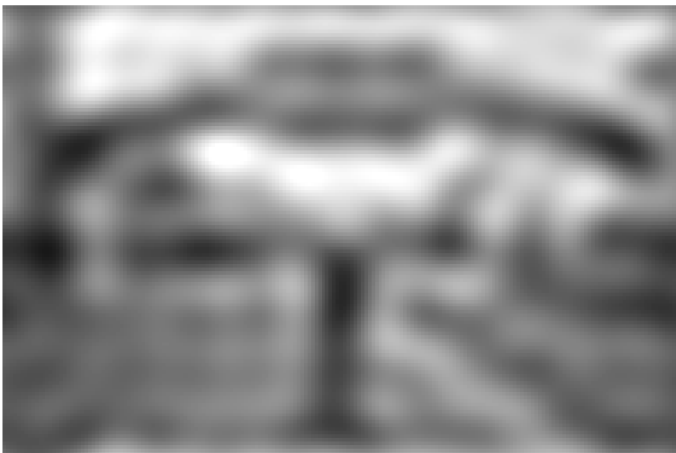
Selecting from the Center: 257 Coefficients

257 of 24,257 coefficients (1.06%)

Selected coefficients



Reconstruction



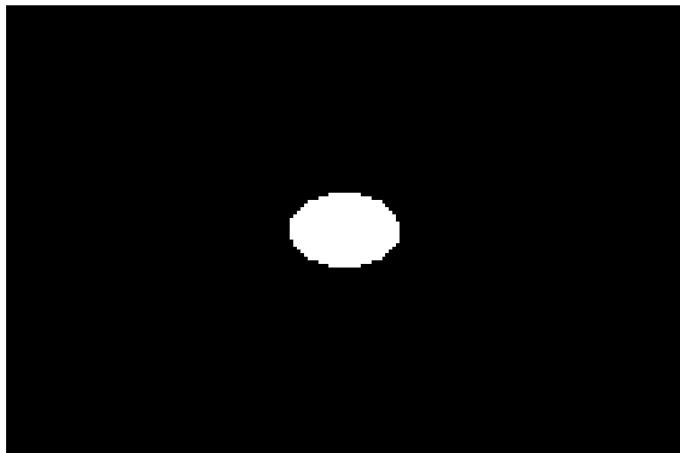
Original



Selecting from the Center: 513 Coefficients

513 of 24,257 coefficients (2.11%)

Selected coefficients



Reconstruction



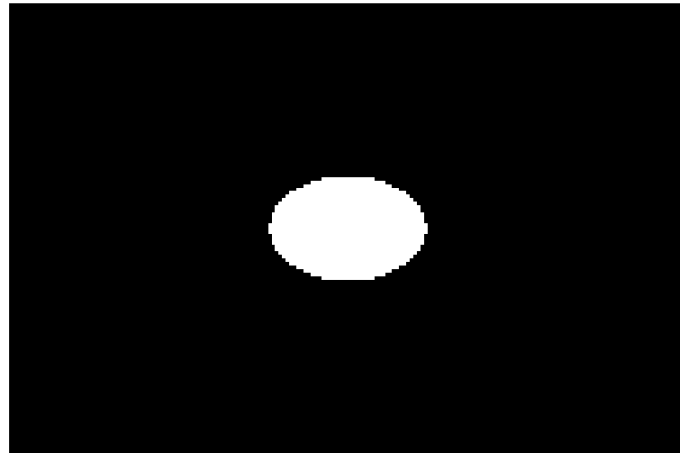
Original



Selecting from the Center: 1,025 Coefficients

1,025 of 24,257 coefficients (4.23%)

Selected coefficients



Reconstruction



Original

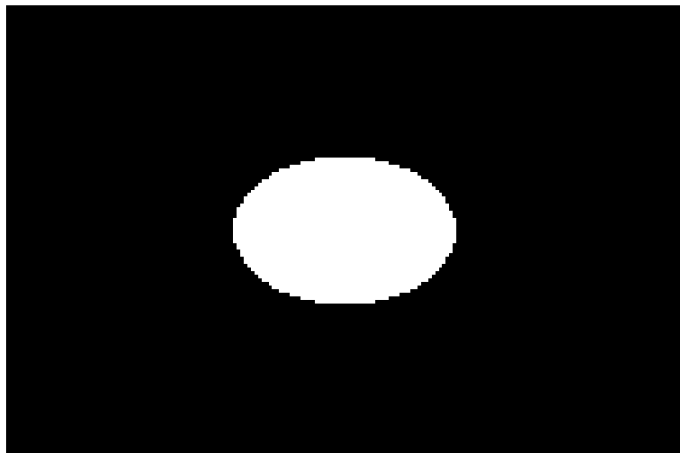


The scene is already recognizable using about **4.2%** of the coefficients.

Selecting from the Center: 2,049 Coefficients

2,049 of 24,257 coefficients (8.45%)

Selected coefficients



Reconstruction



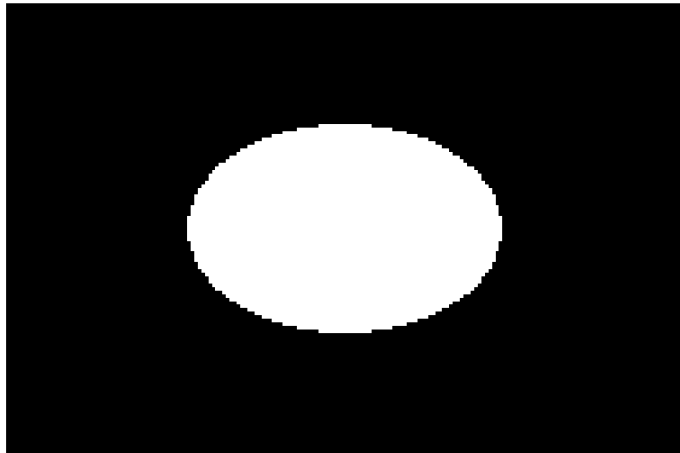
Original



Selecting from the Center: 4,097 Coefficients

4,097 of 24,257 coefficients (16.89%)

Selected coefficients



Reconstruction



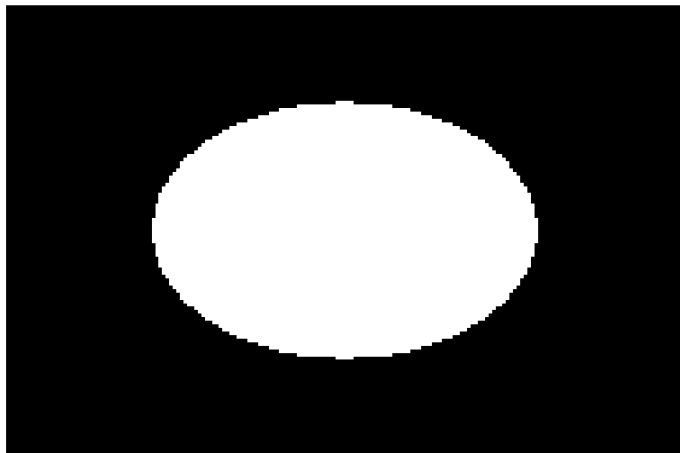
Original



Selecting from the Center: 6,145 Coefficients

6,145 of 24,257 coefficients (25.33%)

Selected coefficients



Reconstruction



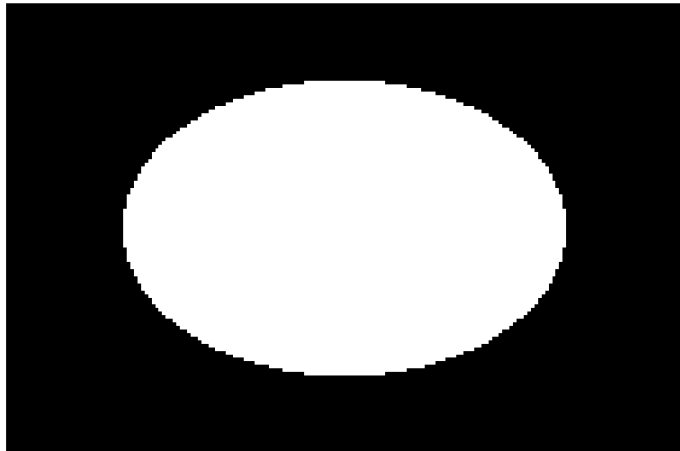
Original



Selecting from the Center: 8,193 Coefficients

8,193 of 24,257 coefficients (33.78%)

Selected coefficients



Reconstruction



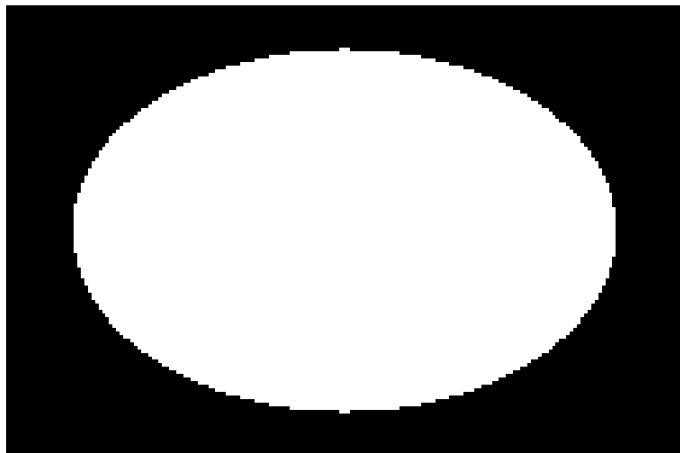
Original



Selecting from the Center: 12,289 Coefficients

12,289 of 24,257 coefficients (50.66%)

Selected coefficients



Reconstruction



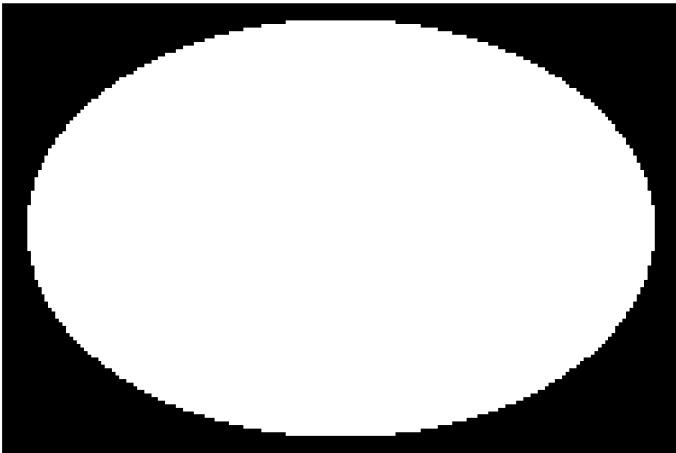
Original



Selecting from the Center: 16,385 Coefficients

16,385 of 24,257 coefficients (67.55%)

Selected coefficients



Reconstruction



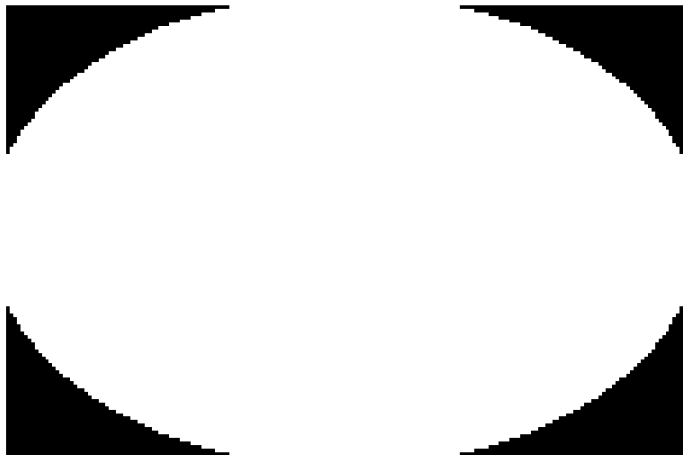
Original



Selecting from the Center: 20,481 Coefficients

20,481 of 24,257 coefficients (84.43%)

Selected coefficients



Reconstruction



Original



Selecting from the Center: All 24,257 Coefficients

24,257 of 24,257 coefficients (100.00%)

Selected coefficients

Reconstruction

Original

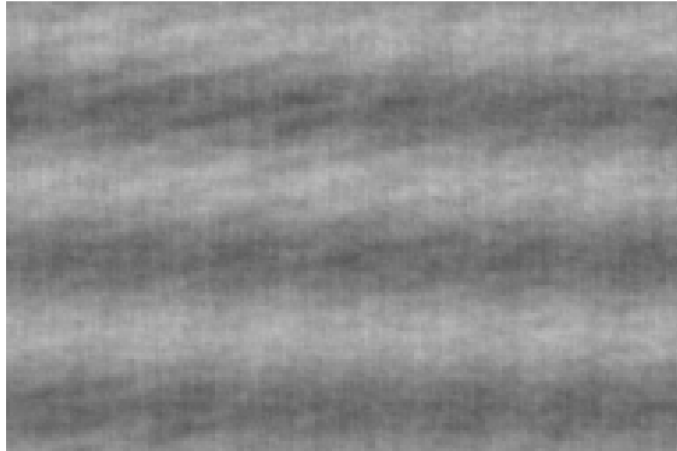


Both methods reach the same exact reconstruction when all coefficients are retained.

Same Number of Coefficients, Different Results

Same budget: 1,025 coefficients (4.23%)

Random selection



Selection from the center



Original

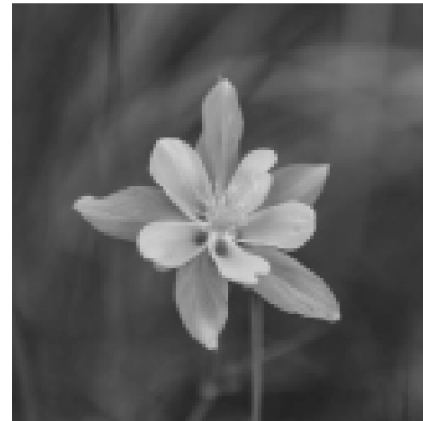


- **Low frequencies** capture much of this image's broad structure.
- Adding **higher frequencies** restores sharper edges and finer details.
- Random selection spends many coefficients on frequencies that contribute little to this image.

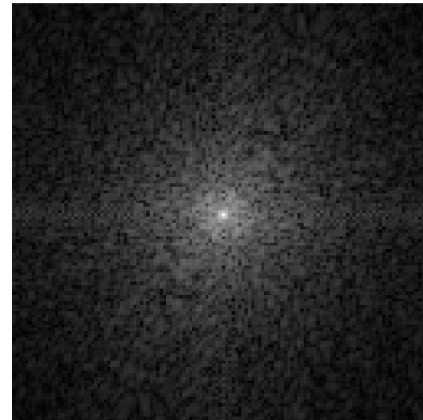
Compression idea: retain informative transform coefficients and encode them efficiently.

Where Is the Energy in Natural Images?

Flower



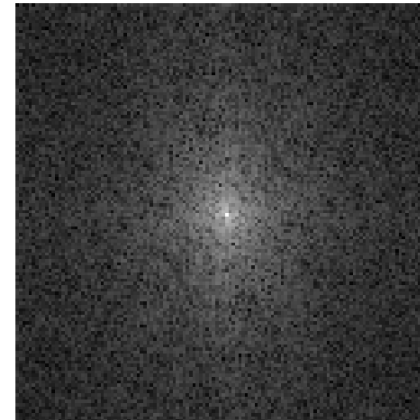
Centered DFT amplitude (log)



Goat



Centered DFT amplitude (log)

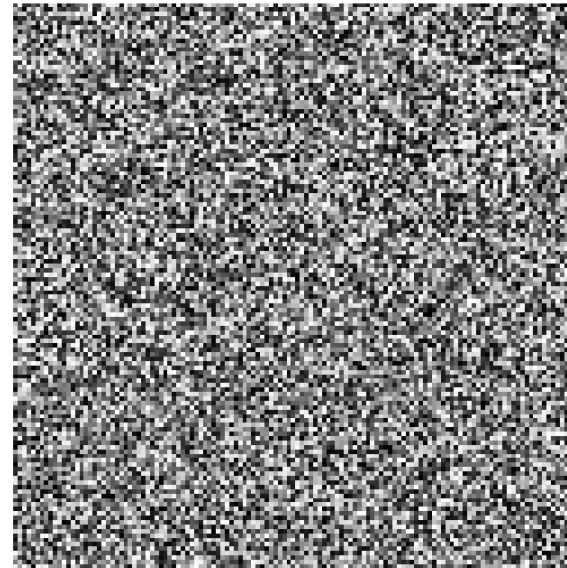


- In many natural images, large amplitudes concentrate **near the center**, at low spatial frequencies.
- **Neighboring pixels often have similar intensities**; edges and fine textures contribute higher frequencies.

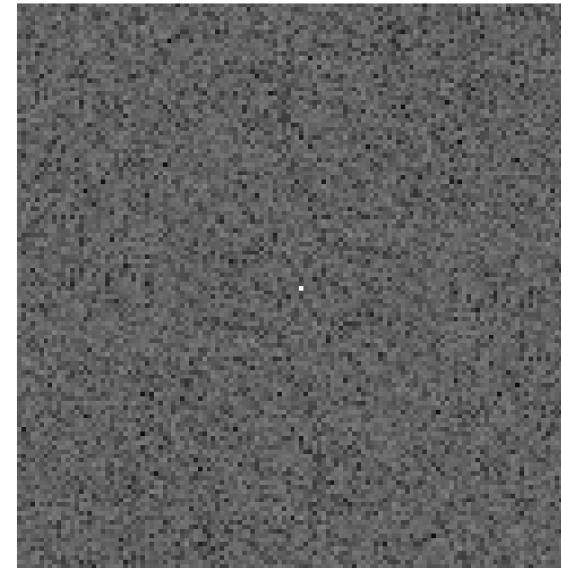
What If Neighboring Pixels Are Unrelated?

Each pixel is drawn **independently** from a uniform distribution between 0 and 1.

Uniform random noise



Centered DFT amplitude (log)



- **Energy is spread broadly across frequencies**, without a strong low-frequency concentration.
- The bright center point is because the image has a nonzero mean.

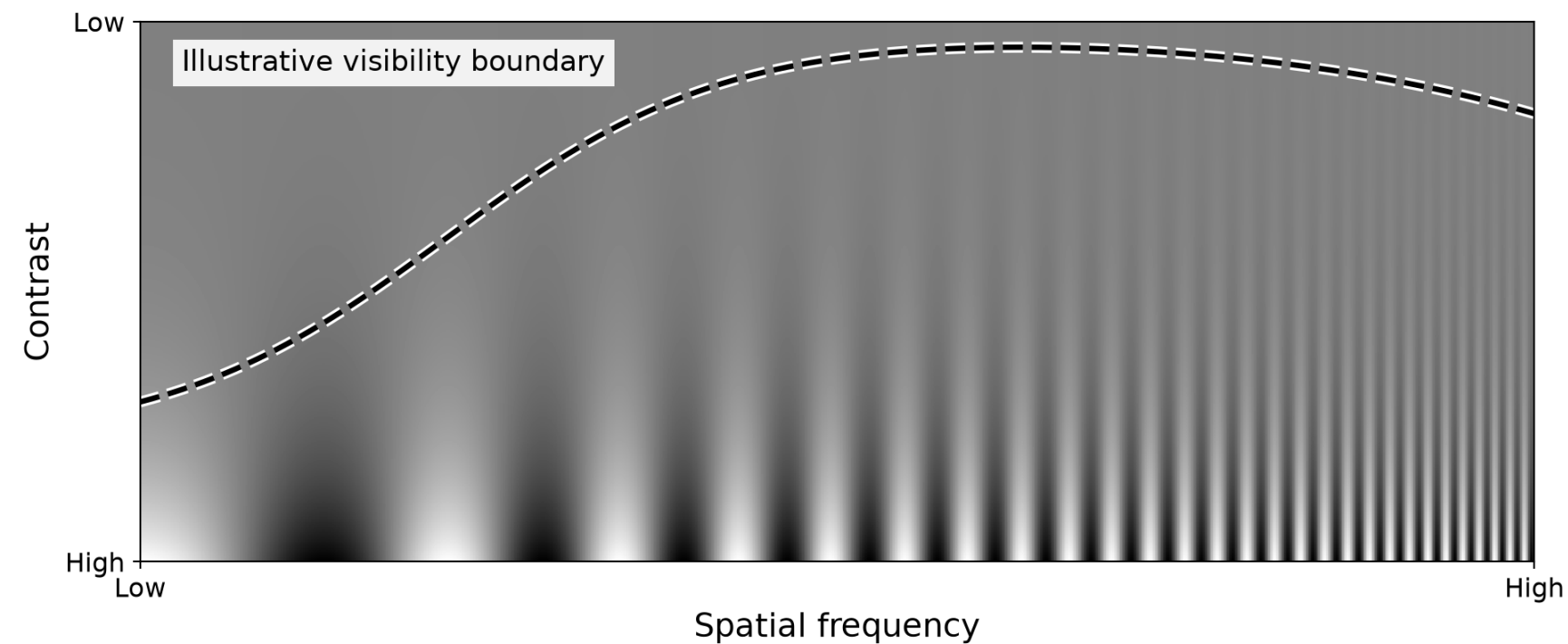
Keeping only low frequencies captures natural-image structure much better than random pixel detail.

Which Frequencies Do We See Best?

Natural images often concentrate energy at **low frequencies**.

Are our eyes equally sensitive to all spatial frequencies?

Where do you see the stripes?



We typically detect **lower contrast at intermediate spatial frequencies** than at very low or very high frequencies.

Note: The curve illustrates the trend. Actual visibility depends on viewing distance, lighting, and the display.

Filtering in the Frequency Domain

A filter changes how strongly different spatial frequencies contribute to an image.

The convolution theorem

Let $F = \mathcal{F}\{I\}$ and $H = \mathcal{F}\{h\}$.

$$y = I * h \quad \Longleftrightarrow \quad Y = FH$$

Therefore,

$$y = \mathcal{F}^{-1}\{FH\}$$

- Convolution in the spatial domain becomes **elementwise multiplication** in the frequency domain.
- We multiply the **complex coefficients**, retaining both amplitude and phase.

Note

For the DFT, sufficient zero-padding may be needed. The DFT assumes the input is periodic. Zero-padding ensures that the filter does not wrap around and affect the opposite edge of the image.

But We Defined Image Filtering as Correlation

In Lecture 3, we used

$$y[m, n] = \sum_k \sum_l h[k, l] I[m + k, n + l].$$

This is **correlation**, as implemented by `cv2.filter2D()`.

For our real-valued kernels:

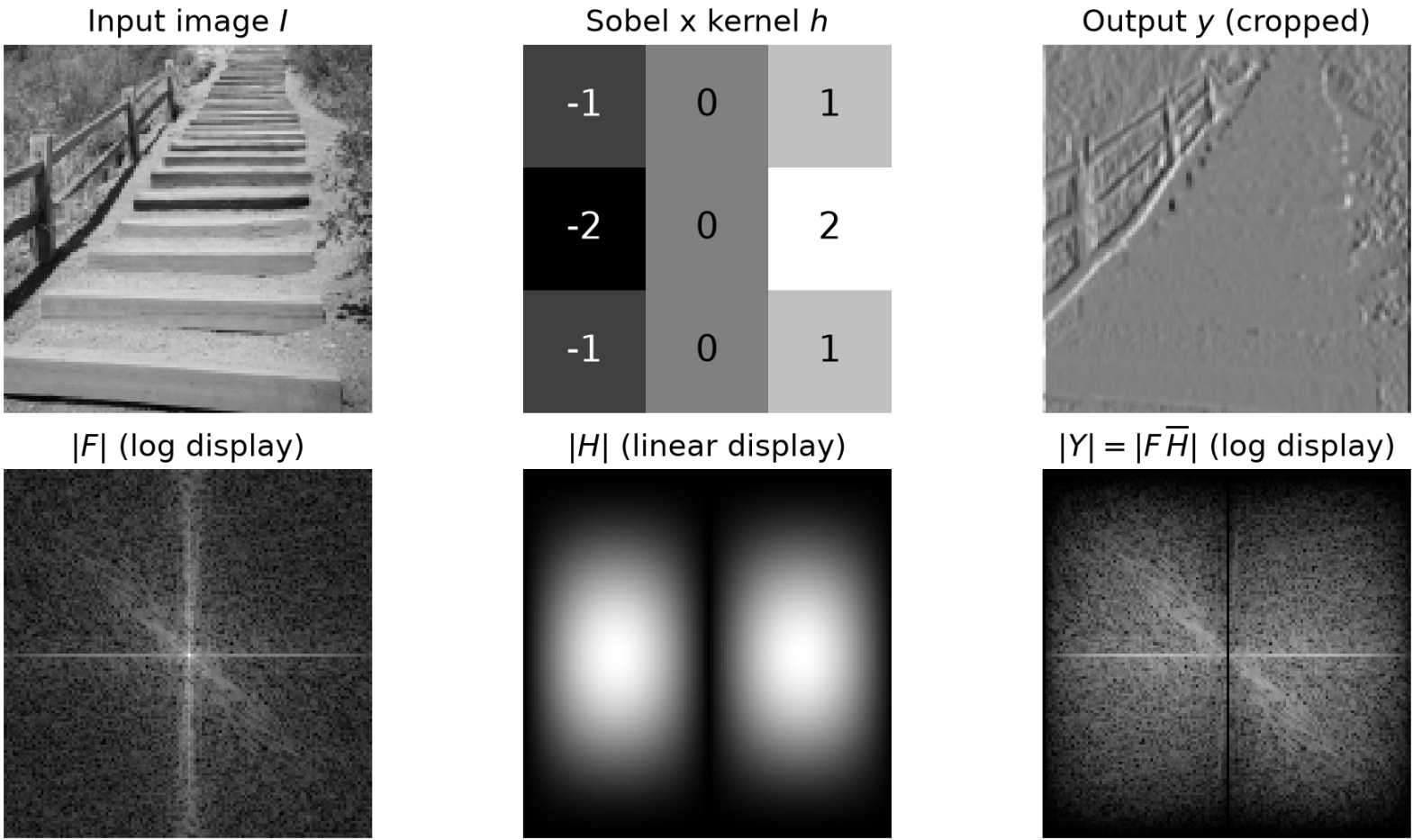
Spatial operation	Frequency-domain operation
Convolution with h	$Y = FH$
Correlation with h	$Y = F\overline{H}$

Here, $\overline{H}$ is the **complex conjugate** of H .

- For **centered, symmetric** kernels such as **box** and **Gaussian filters**, correlation and convolution give the same result.
- For **Sobel x**, switching between them reverses the response's sign.

The Same Filter in Two Domains

$$y = \text{corr}(I, h) \quad \Longleftrightarrow \quad Y = F\overline{H}$$



The Sobel x filter suppresses constant regions and responds to **horizontal intensity changes**, emphasizing vertical edges.

Small Kernel, Full-Sized Spectrum

The spectrum’s dimensions are determined by the DFT grid—not by the number of kernel entries.

For an $M \times N$ image and a $P \times Q$ kernel, a sufficient grid size is

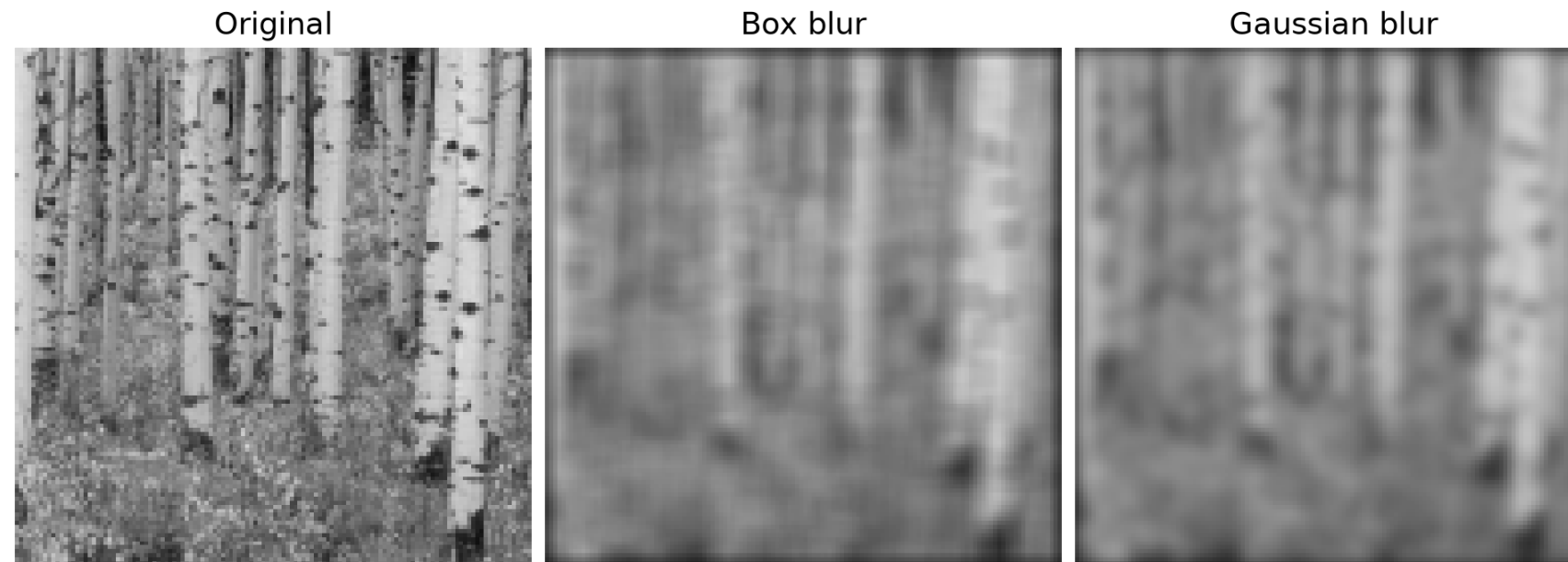
$$(M + P - 1) \times (N + Q - 1).$$

In the last example	Array size
Original image	128×128
Sobel kernel	3×3
Padded image and padded kernel	130×130
Both DFTs	130×130

- **Zero-pad both arrays** so their spectra can be multiplied element by element.
- Place the kernel’s **center at the DFT origin** to align the filtering response correctly.
- Apply the inverse DFT, then **crop to the original image size**.

Revisiting Blurring: Box vs. Gaussian

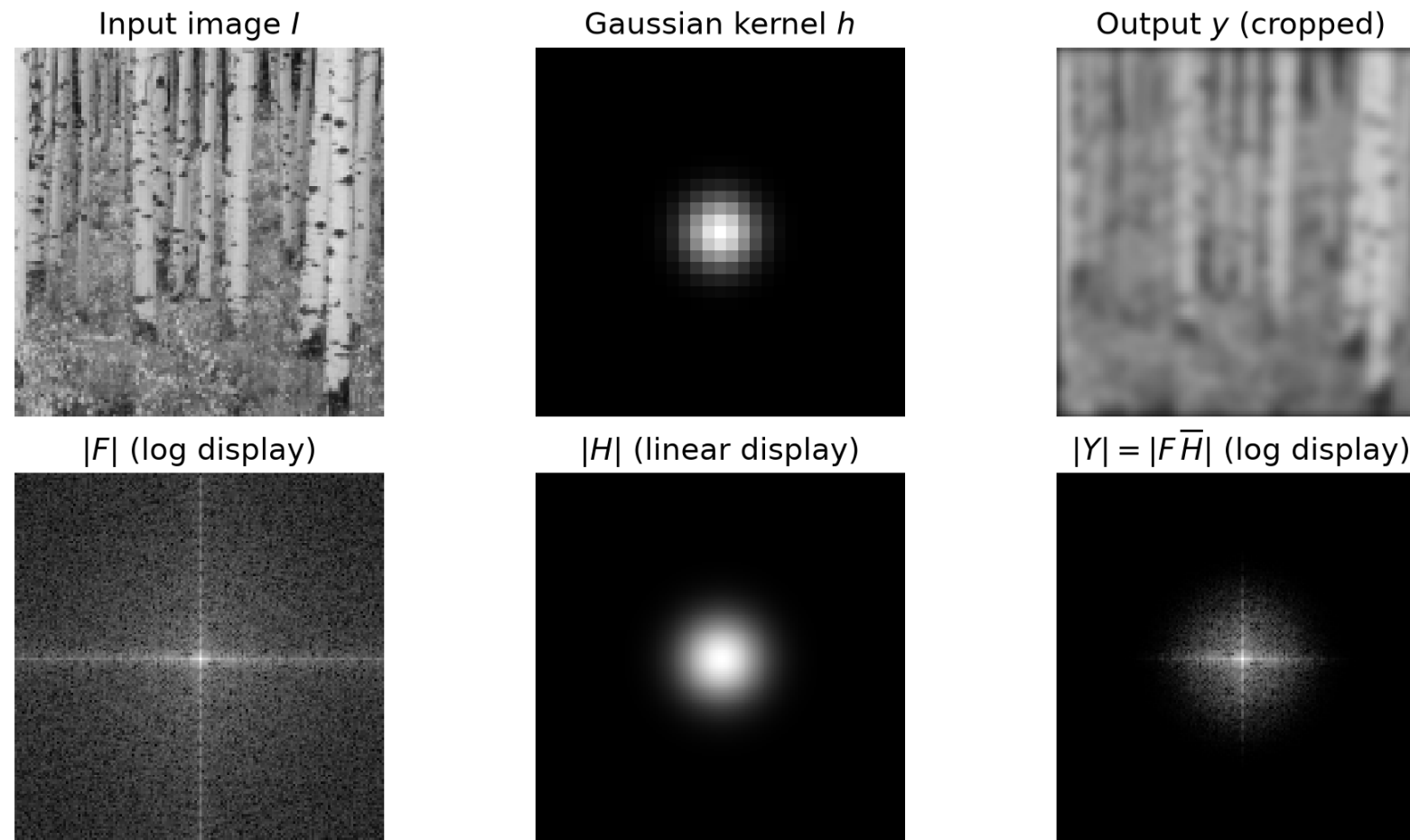
Both filters average neighboring pixels. **Why do their results look different?**



- **Box:** all pixels inside the window receive equal weight.
- **Gaussian:** weights decrease smoothly with distance from the center.

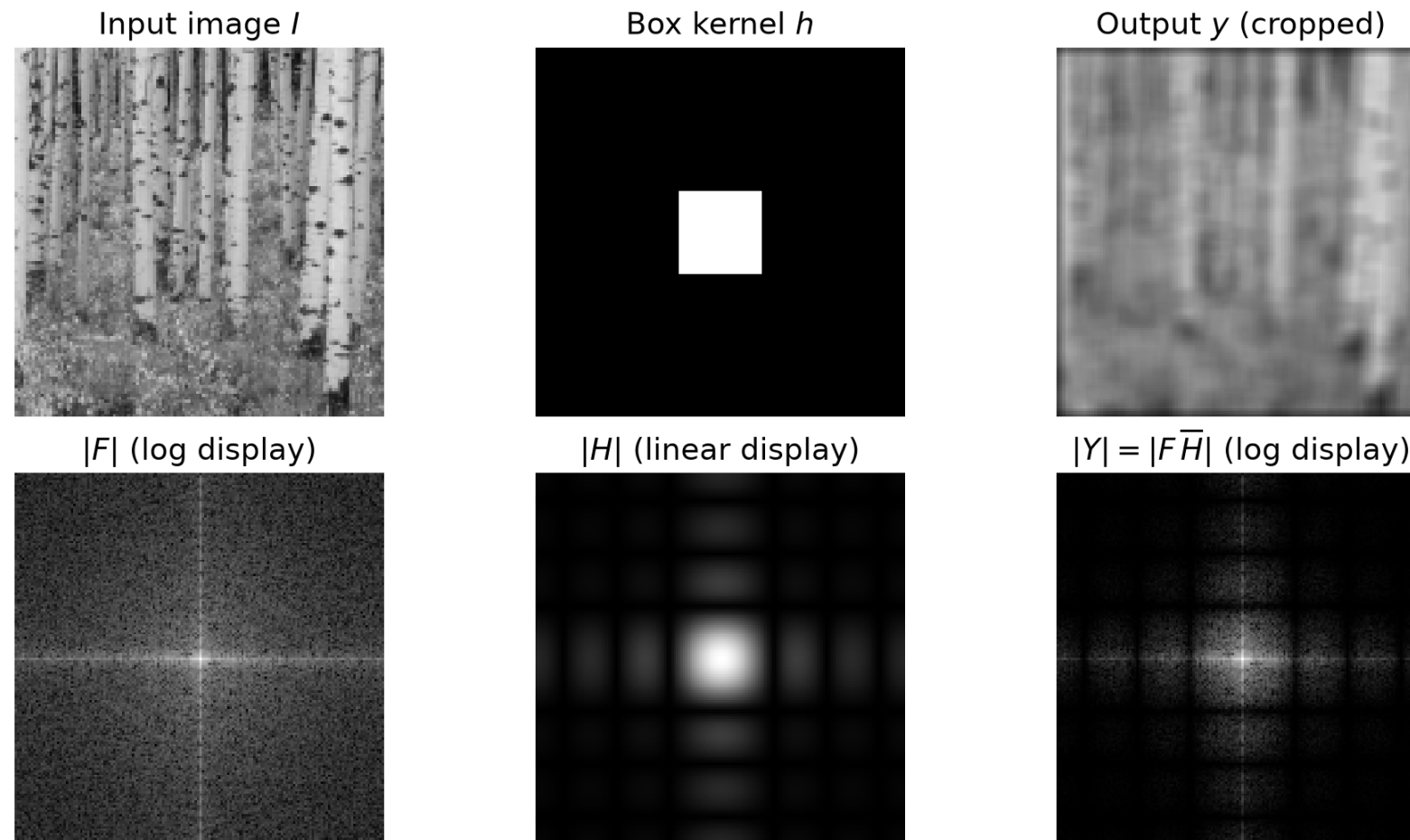
Their Fourier transforms reveal which frequencies each filter preserves or suppresses.

Gaussian Blur in the Frequency Domain



- The frequency response is **Gaussian-shaped**.
- Low frequencies pass through; higher frequencies are progressively attenuated.

Box Blur in the Frequency Domain



- The square kernel produces a **sinc-like response** with zeros and side lobes.
- Some frequency bands are suppressed strongly, while neighboring bands pass through more.
- This less uniform attenuation can leave more visible directional or block-like structure.

Quiz: Match Each Filter to Its Output

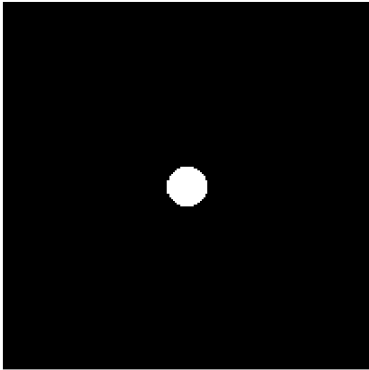
Match frequency-domain filters A–D to output images 1–4.

White passes frequencies; black removes them.

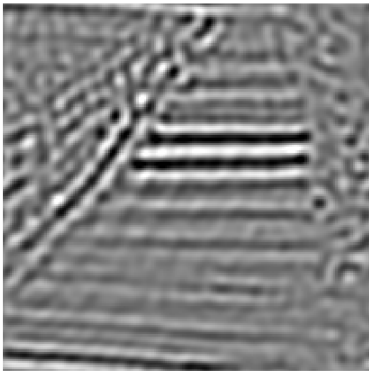
Original



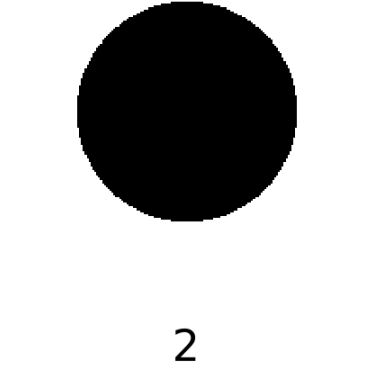
A



1



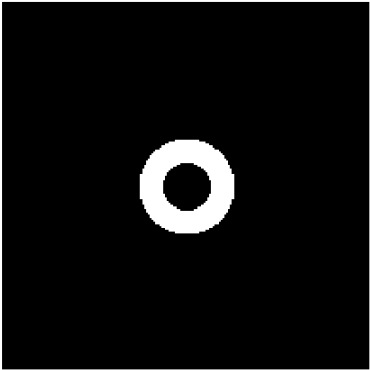
B



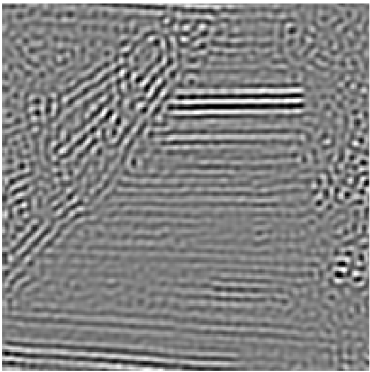
2



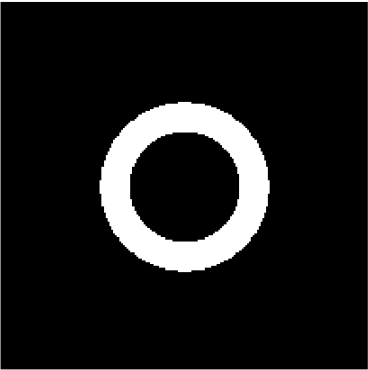
C



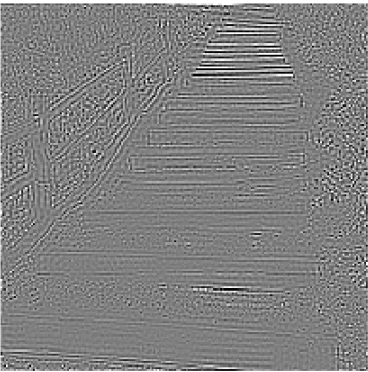
3



D



4



Which filters retain broad structures, intermediate details, or the finest texture?

The Nyquist–Shannon Sampling Theorem

A band-limited signal with highest frequency $f_{\max}$ can be reconstructed from ideal samples when

$f_s > 2f_{\max}$

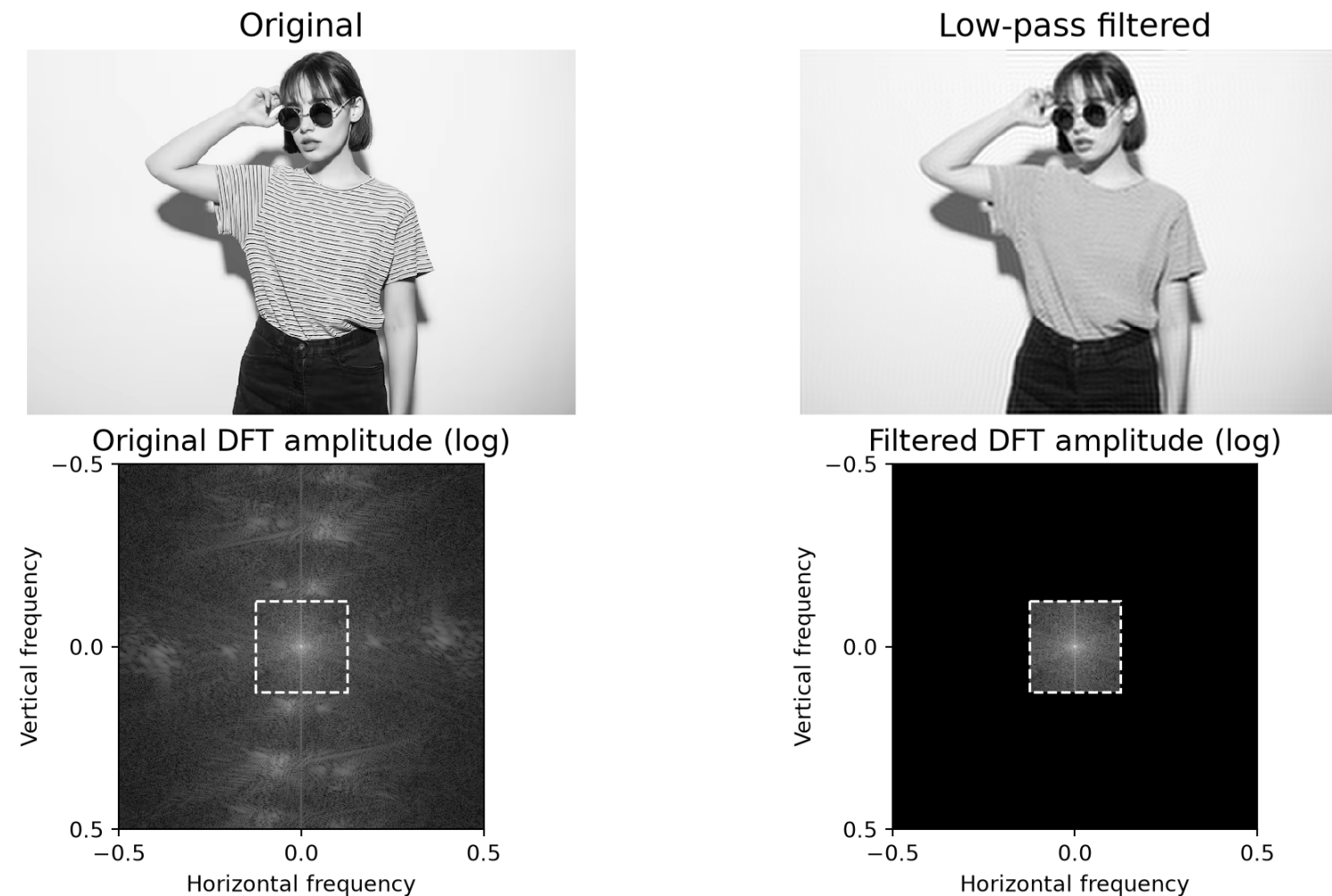
Term	Meaning
Nyquist rate: $2f_{\max}$	Sampling-rate threshold determined by the signal
Nyquist frequency: $f_s/2$	Frequency limit determined by the sampling rate

What happens when we downsample an image?

- The sampling rate decreases, so the image must contain fewer high frequencies.
- Frequencies above the new **Nyquist frequency** ($f_s/2$) fold into lower frequencies, producing aliasing.

Low-Pass Filtering Before Downsampling

Downsampling by 4 lowers the frequency limit to $1/8$ cycle per original pixel in each direction.



- The dashed box marks the frequencies the smaller image can represent.
- We remove frequencies outside that region **before discarding pixels**.

What Happens If We Skip the Filter?

Both downsampled images keep **every fourth row and column**.



- **Without filtering:** fine stripes can become false coarse patterns—**aliasing**.
- **With filtering:** fine detail is deliberately removed before it can fold into lower frequencies.

Losing detail is preferable to inventing a different pattern.

Key Takeaways

- **Fourier representation:** an image can be expressed as a weighted combination of spatial waves.
- **Amplitude and phase:** amplitude describes each component's strength; phase determines its alignment. Reconstruction requires both.
- **Reconstruction and compression:** selected coefficients can capture much of an image's structure; discarded coefficients represent lost information.
- **Filtering:** convolution uses $Y = FH$; correlation with our real-valued kernels uses $Y = F\overline{H}$. Padding and kernel alignment matter.
- **Sampling:** retain frequencies below the new Nyquist limit. Low-pass filtering must happen before downsampling.